

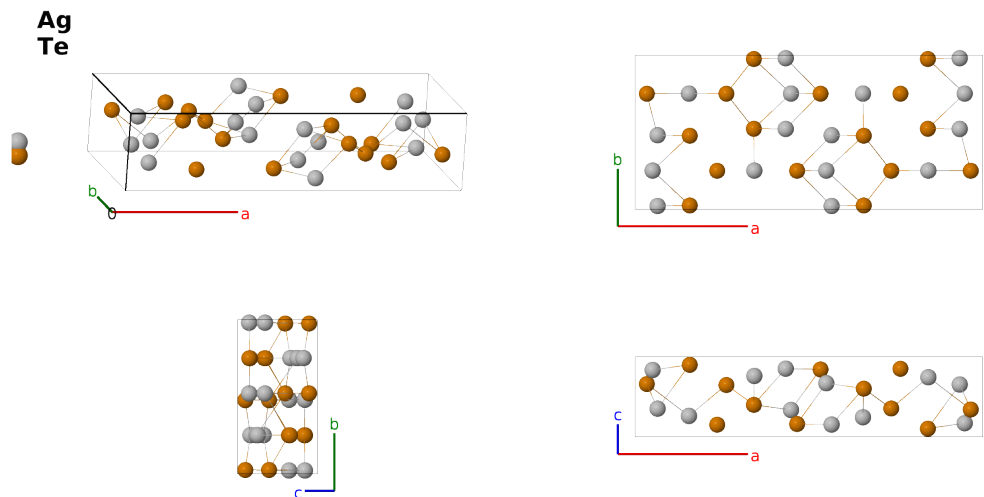
Empressite (AgTe) Structure: AB_oP32_62_2cd_2cd-001

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<https://aflow.org/prototype-encyclopedia/JH5H>

https://aflow.org/prototype-encyclopedia/AB_oP32_62_2cd_2cd-001



Prototype	AgTe
AFLOW prototype label	AB_oP32_62_2cd_2cd-001
Mineral name	empressite
ICSD	55237
CCDC	1619554
Pearson symbol	oP32
Space group number	62
Space group symbol	$Pnma$
AFLOW prototype command	<code>aflow --proto=AB_oP32_62_2cd_2cd-001</code> <code>--params=a,b/a,c/a,x₁,z₁,x₂,z₂,x₃,z₃,x₄,z₄,x₅,y₅,z₅,x₆,y₆,z₆</code>

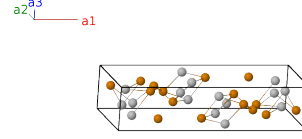
- (Bindi, 2004) give the structural information in the $Pmnb$ setting of space group #62. We used FINDSYM to transform this to the standard $Pnma$ setting.

Simple Orthorhombic primitive vectors

$$\mathbf{a}_1 = a \hat{\mathbf{x}}$$

$$\mathbf{a}_2 = b \hat{\mathbf{y}}$$

$$\mathbf{a}_3 = c \hat{\mathbf{z}}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= x_1 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_1 \mathbf{a}_3$	$=$	$ax_1 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(4c)	Ag I
$\mathbf{B}_2$	$= -(x_1 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(x_1 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Ag I
$\mathbf{B}_3$	$= -x_1 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_1 \mathbf{a}_3$	$=$	$-ax_1 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_1 \hat{\mathbf{z}}$	(4c)	Ag I
$\mathbf{B}_4$	$= (x_1 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	$=$	$a(x_1 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Ag I
$\mathbf{B}_5$	$= x_2 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(4c)	Ag II
$\mathbf{B}_6$	$= -(x_2 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(x_2 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Ag II
$\mathbf{B}_7$	$= -x_2 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$	(4c)	Ag II
$\mathbf{B}_8$	$= (x_2 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$a(x_2 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Ag II
$\mathbf{B}_9$	$= x_3 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(4c)	Te I
$\mathbf{B}_{10}$	$= -(x_3 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(x_3 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Te I
$\mathbf{B}_{11}$	$= -x_3 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_3 \hat{\mathbf{z}}$	(4c)	Te I
$\mathbf{B}_{12}$	$= (x_3 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$a(x_3 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Te I
$\mathbf{B}_{13}$	$= x_4 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$ax_4 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(4c)	Te II
$\mathbf{B}_{14}$	$= -(x_4 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(x_4 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Te II
$\mathbf{B}_{15}$	$= -x_4 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-ax_4 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$	(4c)	Te II
$\mathbf{B}_{16}$	$= (x_4 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$a(x_4 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Te II
$\mathbf{B}_{17}$	$= x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$ax_5 \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8d)	Ag III
$\mathbf{B}_{18}$	$= -(x_5 - \frac{1}{2}) \mathbf{a}_1 - y_5 \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(x_5 - \frac{1}{2}) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	Ag III
$\mathbf{B}_{19}$	$= -x_5 \mathbf{a}_1 + (y_5 + \frac{1}{2}) \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-ax_5 \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$	(8d)	Ag III
$\mathbf{B}_{20}$	$= (x_5 + \frac{1}{2}) \mathbf{a}_1 - (y_5 - \frac{1}{2}) \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$a(x_5 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	Ag III
$\mathbf{B}_{21}$	$= -x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-ax_5 \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$	(8d)	Ag III
$\mathbf{B}_{22}$	$= (x_5 + \frac{1}{2}) \mathbf{a}_1 + y_5 \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$a(x_5 + \frac{1}{2}) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	Ag III
$\mathbf{B}_{23}$	$= x_5 \mathbf{a}_1 - (y_5 - \frac{1}{2}) \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$ax_5 \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8d)	Ag III
$\mathbf{B}_{24}$	$= -(x_5 - \frac{1}{2}) \mathbf{a}_1 + (y_5 + \frac{1}{2}) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(x_5 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	Ag III
$\mathbf{B}_{25}$	$= x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	$=$	$ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8d)	Te III

$$\begin{aligned}
\mathbf{B}_{26} &= \begin{matrix} -\left(x_6 - \frac{1}{2}\right) \mathbf{a}_1 - y_6 \mathbf{a}_2 + \\ \left(z_6 + \frac{1}{2}\right) \mathbf{a}_3 \end{matrix} &= & -a \left(x_6 - \frac{1}{2}\right) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + c \left(z_6 + \frac{1}{2}\right) \hat{\mathbf{z}} & (8d) & \text{Te III} \\
\mathbf{B}_{27} &= -x_6 \mathbf{a}_1 + \left(y_6 + \frac{1}{2}\right) \mathbf{a}_2 - z_6 \mathbf{a}_3 &= & -ax_6 \hat{\mathbf{x}} + b \left(y_6 + \frac{1}{2}\right) \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (8d) & \text{Te III} \\
\mathbf{B}_{28} &= \begin{matrix} \left(x_6 + \frac{1}{2}\right) \mathbf{a}_1 - \left(y_6 - \frac{1}{2}\right) \mathbf{a}_2 - \\ \left(z_6 - \frac{1}{2}\right) \mathbf{a}_3 \end{matrix} &= & a \left(x_6 + \frac{1}{2}\right) \hat{\mathbf{x}} - b \left(y_6 - \frac{1}{2}\right) \hat{\mathbf{y}} - c \left(z_6 - \frac{1}{2}\right) \hat{\mathbf{z}} & (8d) & \text{Te III} \\
\mathbf{B}_{29} &= -x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3 &= & -ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (8d) & \text{Te III} \\
\mathbf{B}_{30} &= \left(x_6 + \frac{1}{2}\right) \mathbf{a}_1 + y_6 \mathbf{a}_2 - \left(z_6 - \frac{1}{2}\right) \mathbf{a}_3 &= & a \left(x_6 + \frac{1}{2}\right) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} - c \left(z_6 - \frac{1}{2}\right) \hat{\mathbf{z}} & (8d) & \text{Te III} \\
\mathbf{B}_{31} &= x_6 \mathbf{a}_1 - \left(y_6 - \frac{1}{2}\right) \mathbf{a}_2 + z_6 \mathbf{a}_3 &= & ax_6 \hat{\mathbf{x}} - b \left(y_6 - \frac{1}{2}\right) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (8d) & \text{Te III} \\
\mathbf{B}_{32} &= \begin{matrix} -\left(x_6 - \frac{1}{2}\right) \mathbf{a}_1 + \left(y_6 + \frac{1}{2}\right) \mathbf{a}_2 + \\ \left(z_6 + \frac{1}{2}\right) \mathbf{a}_3 \end{matrix} &= & -a \left(x_6 - \frac{1}{2}\right) \hat{\mathbf{x}} + b \left(y_6 + \frac{1}{2}\right) \hat{\mathbf{y}} + c \left(z_6 + \frac{1}{2}\right) \hat{\mathbf{z}} & (8d) & \text{Te III}
\end{aligned}$$

References

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First cited in

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