

δ -Bi₂O₃ Structure:

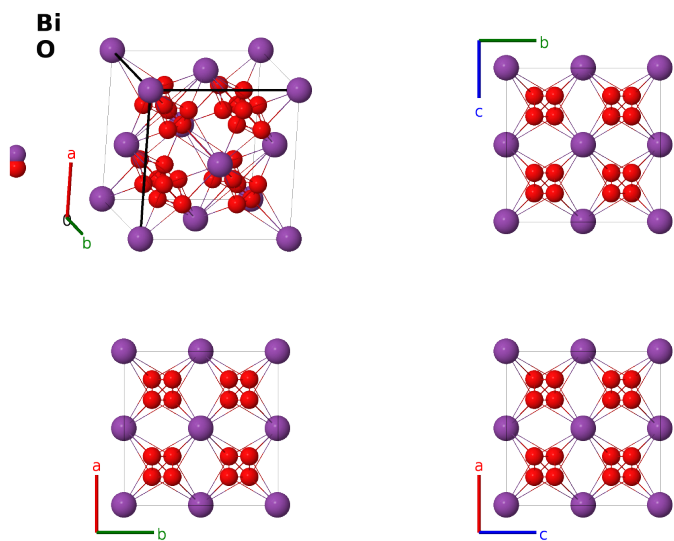
AB8_cF36_225_a_f-001

Cite this page as:

- H. Eckert, S. Divilov, M. J. Mehl, D. Hicks, A. C. Zettl, M. Esters, X. Campilongo, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*, Comput. Mater. Sci. **240**, 112988 (2024), doi: 10.1016/j.commatsci.2024.112988.
- D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

<https://aflow.org/prototype-encyclopedia/X2Q7>

https://aflow.org/prototype-encyclopedia/AB8_cF36_225_a_f-001



Prototype	Bi ₂ O ₃
AFLOW prototype label	AB8_cF36_225_a_f-001
ICSD	2375
CCDC	1592277
Pearson symbol	cF36
Space group number	225
Space group symbol	$Fm\bar{3}m$
AFLOW prototype command	<pre>aflow --proto=AB8_cF36_225_a_f-001 --params=a, x₂</pre>

Other compounds with this structure

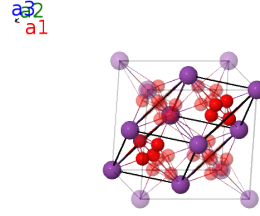
α -CuI, γ -CuI

- Bi₂O₃ can be found in at least six forms (Harwig, 1978; Locherer, 2011):
 - monoclinic α -Bi₂O₃, the ground state, stable up to 729°,
 - tetragonal β -Bi₂O₃, D_{5h} , a metastable state observed at 650°C (this structure),

- body-centered cubic γ - Bi_2O_3 , another metastable phase observed at 639°C ,
 - face-centered cubic δ - Bi_2O_3 , the stable phase from 729° up to the melting point at 824°C (this structure),
 - a high-pressure HP- Bi_2O_3 , and
 - a second “nonquenchable” high-pressure structure, HPC- Bi_2O_3 .
- The oxygen sites are occupied 18.75% of the time. If $z_2 \rightarrow 1/4$, they coalesce on the (2c) Wyckoff position, and this becomes the fluorite (C1) structure.
 - Other compounds with different stoichiometries have this structure. In copper(I) iodide both the high temperature α -CuI and the ground state γ -CuI phases are in this structure, with the copper atoms occupying 1/8 of the (32f) sites. (Keen, 1995)

Face-centered Cubic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$=$	0	$=$	0	(4a) Bi I
$\mathbf{B}_2$	$=$	$x_2 \mathbf{a}_1 + x_2 \mathbf{a}_2 + x_2 \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} + ax_2 \hat{\mathbf{z}}$	(32f) O I
$\mathbf{B}_3$	$=$	$x_2 \mathbf{a}_1 + x_2 \mathbf{a}_2 - 3x_2 \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} + ax_2 \hat{\mathbf{z}}$	(32f) O I
$\mathbf{B}_4$	$=$	$x_2 \mathbf{a}_1 - 3x_2 \mathbf{a}_2 + x_2 \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} - ax_2 \hat{\mathbf{z}}$	(32f) O I
$\mathbf{B}_5$	$=$	$-3x_2 \mathbf{a}_1 + x_2 \mathbf{a}_2 + x_2 \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} - ax_2 \hat{\mathbf{z}}$	(32f) O I
$\mathbf{B}_6$	$=$	$-x_2 \mathbf{a}_1 - x_2 \mathbf{a}_2 + 3x_2 \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} - ax_2 \hat{\mathbf{z}}$	(32f) O I
$\mathbf{B}_7$	$=$	$-x_2 \mathbf{a}_1 - x_2 \mathbf{a}_2 - x_2 \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} - ax_2 \hat{\mathbf{z}}$	(32f) O I
$\mathbf{B}_8$	$=$	$-x_2 \mathbf{a}_1 + 3x_2 \mathbf{a}_2 - x_2 \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} + ax_2 \hat{\mathbf{z}}$	(32f) O I
$\mathbf{B}_9$	$=$	$3x_2 \mathbf{a}_1 - x_2 \mathbf{a}_2 - x_2 \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} + ax_2 \hat{\mathbf{z}}$	(32f) O I

References

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Found in

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First cited in

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