

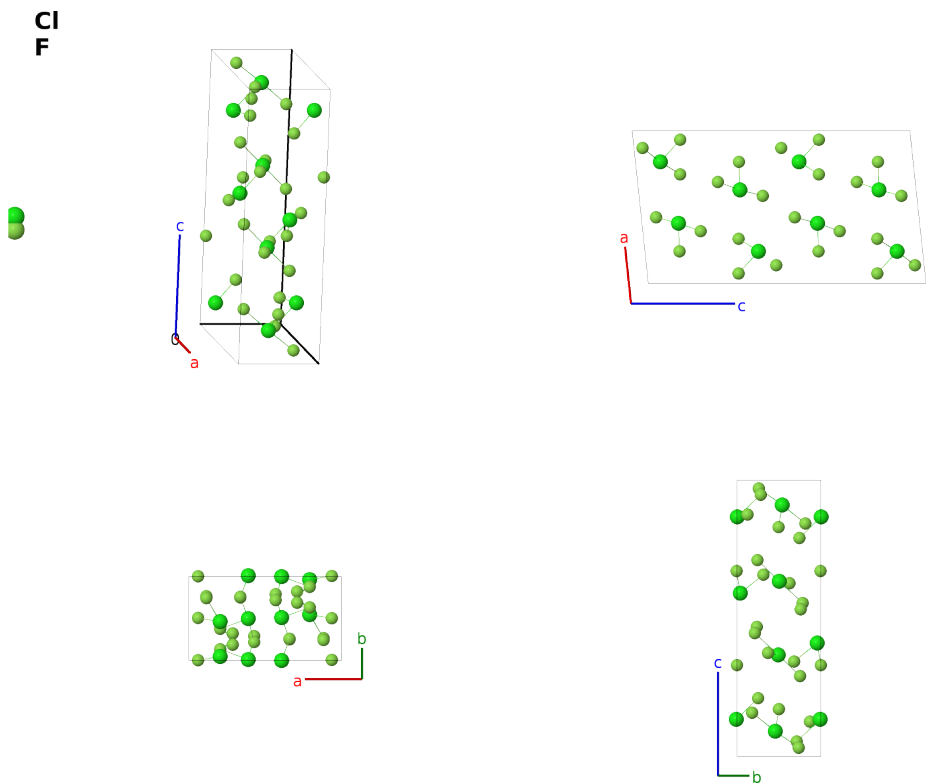
Monoclinic ClF₃ Structure: AB3_mP32_14_2e_6e-001

Cite this page as:

- H. Eckert, S. Divilov, M. J. Mehl, D. Hicks, A. C. Zettel, M. Esters, X. Campilongo, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*, Comput. Mater. Sci. **240**, 112988 (2024), doi: 10.1016/j.commatsci.2024.112988.
- D. Hicks, M. J. Mehl, M. Esters, C. Osos, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

<https://aflow.org/prototype-encyclopedia/4D8B>

https://aflow.org/prototype-encyclopedia/AB3_mP32_14_2e_6e-001

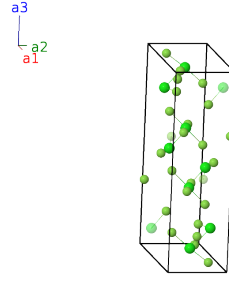


Prototype	ClF ₃
AFLOW prototype label	AB3_mP32_14_2e_6e-001
ICSD	203121
CCDC	1707675
Pearson symbol	mP32
Space group number	14
Space group symbol	$P2_1/c$
AFLOW prototype command	<pre>aflow --proto=AB3_mP32_14_2e_6e-001 --params=a,b/a,c/a,β,x₁,y₁,z₁,x₂,y₂,z₂,x₃,y₃,z₃,x₄,y₄,z₄,x₅,y₅,z₅,x₆,y₆,z₆,x₇,y₇,z₇,x₈,y₈,z₈</pre>

- Solid ClF_3 is known to exist in several structures (Villars, 2018):
 - From -83°C to the melting point it takes on the current structure.
 - Between -109 and -100°C it takes on an orthorhombic structure with 4 formula units in the primitive cell.
 - Below -109°C there is another structure for which we have no data.
 - (Villars, 2018) give no data on the structure between -100 and -83°C .
- ClF_3 is extremely dangerous in any of these forms.
- Monoclinic ClFe_3 and CrTe_3 have the same AFLOW prototype label, `AB3_mP32_14_2e_6e`. This label is similar to that of $\gamma\text{-WO}_3$, `A3B_mP32_14_6e_2e`. The unique structures are generated by the same symmetry operations with different sets of parameters (`--params`) specified in their corresponding CIF files.

Simple Monoclinic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates		Wyckoff position	Atom type
$\mathbf{B}_1$	$= x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	$=$	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)		Cl I
$\mathbf{B}_2$	$= -x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)		Cl I
$\mathbf{B}_3$	$= -x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	$=$	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)		Cl I
$\mathbf{B}_4$	$= x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)		Cl I
$\mathbf{B}_5$	$= x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)		Cl II
$\mathbf{B}_6$	$= -x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)		Cl II
$\mathbf{B}_7$	$= -x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)		Cl II
$\mathbf{B}_8$	$= x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)		Cl II
$\mathbf{B}_9$	$= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)		F I
$\mathbf{B}_{10}$	$= -x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)		F I
$\mathbf{B}_{11}$	$= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)		F I
$\mathbf{B}_{12}$	$= x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)		F I
$\mathbf{B}_{13}$	$= x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)		F II

$$\begin{aligned}
\mathbf{B}_{14} &= -x_4 \mathbf{a}_1 + \left(y_4 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_4 - \frac{1}{2}\right) \mathbf{a}_3 &= -\left(ax_4 + c\left(z_4 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_4 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_4 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F II} \\
\mathbf{B}_{15} &= -x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3 &= -(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}} &(4e) &\text{F II} \\
\mathbf{B}_{16} &= x_4 \mathbf{a}_1 - \left(y_4 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_4 + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_4 + c\left(z_4 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_4 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_4 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F II} \\
\mathbf{B}_{17} &= x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3 &= (ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}} &(4e) &\text{F III} \\
\mathbf{B}_{18} &= -x_5 \mathbf{a}_1 + \left(y_5 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_5 - \frac{1}{2}\right) \mathbf{a}_3 &= -\left(ax_5 + c\left(z_5 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_5 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_5 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F III} \\
\mathbf{B}_{19} &= -x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3 &= -(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}} &(4e) &\text{F III} \\
\mathbf{B}_{20} &= x_5 \mathbf{a}_1 - \left(y_5 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_5 + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_5 + c\left(z_5 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_5 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_5 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F III} \\
\mathbf{B}_{21} &= x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3 &= (ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}} &(4e) &\text{F IV} \\
\mathbf{B}_{22} &= -x_6 \mathbf{a}_1 + \left(y_6 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_6 - \frac{1}{2}\right) \mathbf{a}_3 &= -\left(ax_6 + c\left(z_6 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_6 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_6 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F IV} \\
\mathbf{B}_{23} &= -x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3 &= -(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}} &(4e) &\text{F IV} \\
\mathbf{B}_{24} &= x_6 \mathbf{a}_1 - \left(y_6 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_6 + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_6 + c\left(z_6 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_6 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_6 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F IV} \\
\mathbf{B}_{25} &= x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3 &= (ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}} &(4e) &\text{F V} \\
\mathbf{B}_{26} &= -x_7 \mathbf{a}_1 + \left(y_7 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_7 - \frac{1}{2}\right) \mathbf{a}_3 &= -\left(ax_7 + c\left(z_7 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_7 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_7 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F V} \\
\mathbf{B}_{27} &= -x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3 &= -(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}} &(4e) &\text{F V} \\
\mathbf{B}_{28} &= x_7 \mathbf{a}_1 - \left(y_7 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_7 + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_7 + c\left(z_7 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_7 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_7 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F V} \\
\mathbf{B}_{29} &= x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3 &= (ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}} &(4e) &\text{F VI} \\
\mathbf{B}_{30} &= -x_8 \mathbf{a}_1 + \left(y_8 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_8 - \frac{1}{2}\right) \mathbf{a}_3 &= -\left(ax_8 + c\left(z_8 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_8 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_8 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F VI} \\
\mathbf{B}_{31} &= -x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3 &= -(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}} &(4e) &\text{F VI} \\
\mathbf{B}_{32} &= x_8 \mathbf{a}_1 - \left(y_8 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_8 + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_8 + c\left(z_8 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_8 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_8 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} &(4e) &\text{F VI}
\end{aligned}$$

References

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First cited in

- H. Eckert, S. Divilov, M. J. Mehl, D. Hicks, A. C. Zettel, M. Esters, X. Campilongo, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*, Comput. Mater. Sci. **240**, 112988 (2024), doi: 10.1016/j.commatsci.2024.112988.