

Rhombohedral BaTiO₃ Structure:

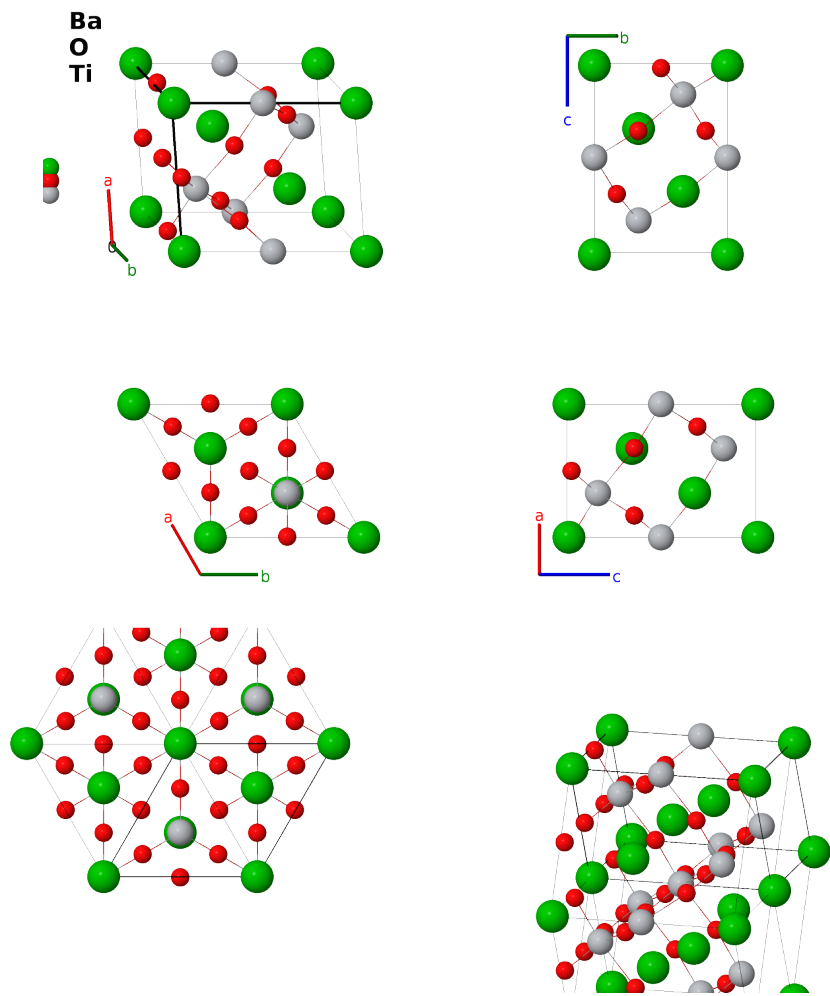
AB3C_hR5_160_a_b_a-001

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<https://aflow.org/prototype-encyclopedia/X85U>

https://aflow.org/prototype-encyclopedia/AB3C_hR5_160_a_b_a-001



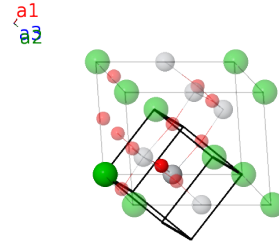
Prototype	BaO ₃ Ti
AFLOW prototype label	AB3C_hR5_160_a_b_a-001
ICSD	6102
CCDC	1593610
Pearson symbol	hR5
Space group number	160

Space group symbol	$R3m$
AFLOW prototype command	aflow --proto=AB3C_hr5_160_a_b_a-001 --params= $a, c/a, x_1, x_2, x_3, z_3$

- The perovskite BaTiO_3 undergoes a variety of temperature driven phase transitions. (Shirane, 1957)
- The first three structures are ferroelectric:
 - Below 193K the structure is rhombohedral. (This structure)
 - Between 193K and 278K the structure is orthorhombic.
 - Between 278K and 393K the structure is tetragonal. This is the room-temperature form of the material.
 - Above 393K the compound is a cubic perovskite ($E2_1$).
- Hexagonal BaTiO_3 can be stabilized by alloying the titanium sites with other transition metals. (Dickson, 1961) The pure structure has been grown at 1853K and cooled to room temperature. (Akimo, 1994)
- The data was taken at 77.4K.
- Rhombohedral BaTiO_3 is isostructural with $\gamma\text{-KNO}_3$ and KBrO_3 ($G0_7$), but the structural parameters are sufficiently different to warrant adding another structure to the database.
- Space group $R3m$ #160 does not specify the origin of the z -axis. We follow (Hewat, 1974) and place the origin so that the titanium atom is at $1/2c\hat{z}$.
- Hexagonal settings of this structure can be obtained with the option `--hex`.

Rhombohedral primitive vectors

$$\begin{aligned}
 \mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a \hat{\mathbf{y}} + \frac{1}{3}c \hat{\mathbf{z}} \\
 \mathbf{a}_2 &= \frac{1}{\sqrt{3}}a \hat{\mathbf{y}} + \frac{1}{3}c \hat{\mathbf{z}} \\
 \mathbf{a}_3 &= -\frac{1}{2}a \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a \hat{\mathbf{y}} + \frac{1}{3}c \hat{\mathbf{z}}
 \end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= x_1 \mathbf{a}_1 + x_1 \mathbf{a}_2 + x_1 \mathbf{a}_3$	$=$	$cx_1 \hat{\mathbf{z}}$	(1a)	Ba I
$\mathbf{B}_2$	$= x_2 \mathbf{a}_1 + x_2 \mathbf{a}_2 + x_2 \mathbf{a}_3$	$=$	$cx_2 \hat{\mathbf{z}}$	(1a)	Ti I
$\mathbf{B}_3$	$= x_3 \mathbf{a}_1 + x_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$\frac{1}{2}a(x_3 - z_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 - z_3) \hat{\mathbf{y}} + \frac{1}{3}c(2x_3 + z_3) \hat{\mathbf{z}}$	(3b)	O I
$\mathbf{B}_4$	$= z_3 \mathbf{a}_1 + x_3 \mathbf{a}_2 + x_3 \mathbf{a}_3$	$=$	$-\frac{1}{2}a(x_3 - z_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 - z_3) \hat{\mathbf{y}} + \frac{1}{3}c(2x_3 + z_3) \hat{\mathbf{z}}$	(3b)	O I
$\mathbf{B}_5$	$= x_3 \mathbf{a}_1 + z_3 \mathbf{a}_2 + x_3 \mathbf{a}_3$	$=$	$-\frac{1}{\sqrt{3}}a(x_3 - z_3) \hat{\mathbf{y}} + \frac{1}{3}c(2x_3 + z_3) \hat{\mathbf{z}}$	(3b)	O I

References

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