

# AgRuO<sub>3</sub> Structure:

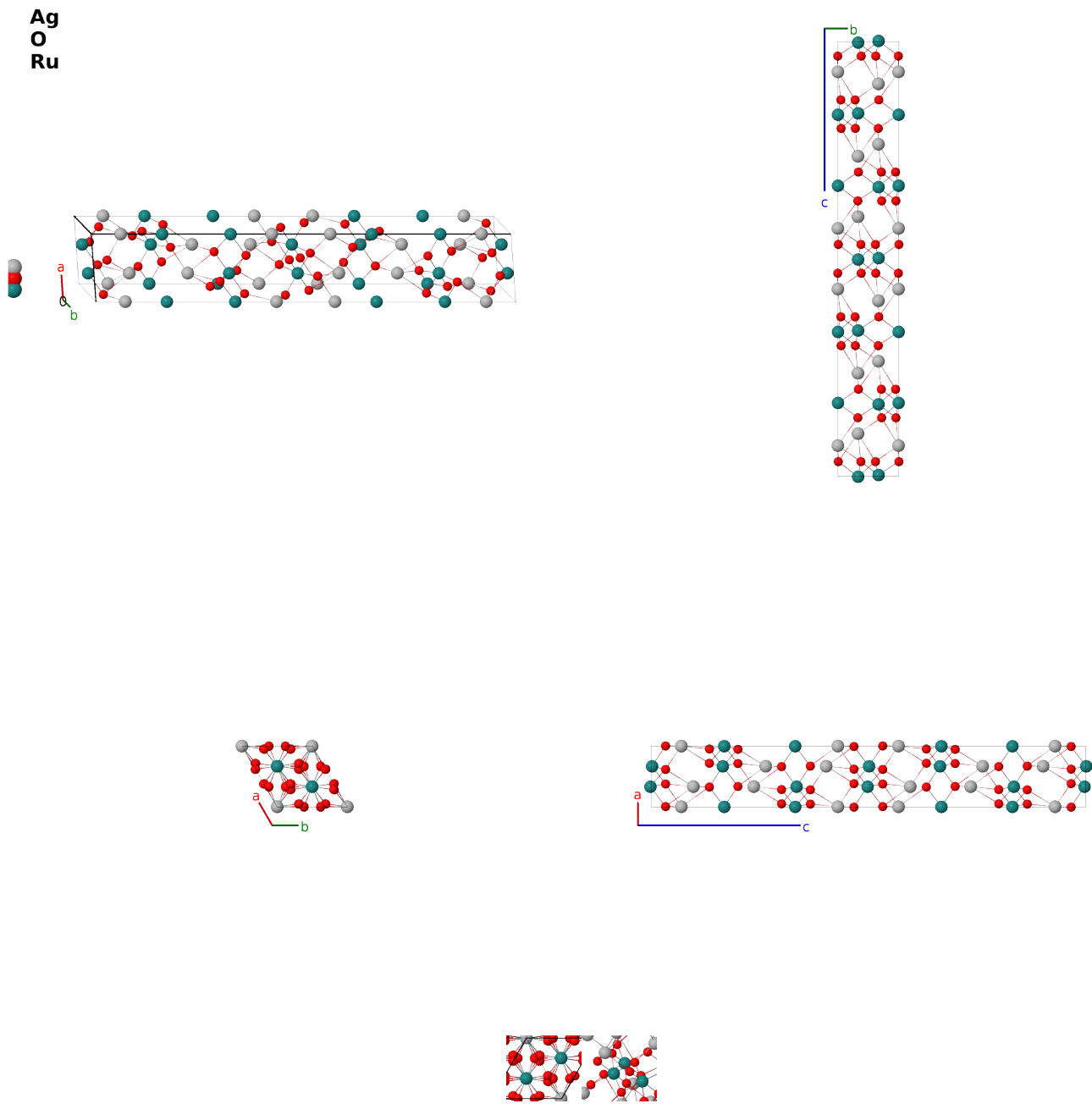
## AB3C\_hR20\_167\_c\_f\_c-001

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<https://aflow.org/prototype-encyclopedia/QQE1>

[https://aflow.org/prototype-encyclopedia/AB3C\\_hR20\\_167\\_c\\_f\\_c-001](https://aflow.org/prototype-encyclopedia/AB3C_hR20_167_c_f_c-001)



Prototype

AgO<sub>3</sub>Ru

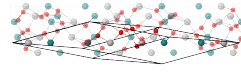
|                         |                                                                                      |
|-------------------------|--------------------------------------------------------------------------------------|
| AFLOW prototype label   | AB3C_hR20_167_c.f.c-001                                                              |
| ICSD                    | 432362                                                                               |
| CCDC                    | 1791377                                                                              |
| Pearson symbol          | hR20                                                                                 |
| Space group number      | 167                                                                                  |
| Space group symbol      | $R\bar{3}c$                                                                          |
| AFLOW prototype command | aflow --proto=AB3C_hR20_167_c.f.c-001<br>--params= $a, c/a, x_1, x_2, x_3, y_3, z_3$ |

- Hexagonal settings of this structure can be obtained with the option `--hex`.

### Rhombohedral primitive vectors

$$\begin{aligned}
\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a \hat{\mathbf{y}} + \frac{1}{3}c \hat{\mathbf{z}} \\
\mathbf{a}_2 &= \frac{1}{\sqrt{3}}a \hat{\mathbf{y}} + \frac{1}{3}c \hat{\mathbf{z}} \\
\mathbf{a}_3 &= -\frac{1}{2}a \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a \hat{\mathbf{y}} + \frac{1}{3}c \hat{\mathbf{z}}
\end{aligned}$$

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### Basis vectors

|                   | Lattice<br>coordinates                                                                                                                       |     | Cartesian<br>coordinates                                                                                                                              | Wyckoff<br>position | Atom<br>type |
|-------------------|----------------------------------------------------------------------------------------------------------------------------------------------|-----|-------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------|--------------|
| $\mathbf{B}_1$    | $= x_1 \mathbf{a}_1 + x_1 \mathbf{a}_2 + x_1 \mathbf{a}_3$                                                                                   | $=$ | $cx_1 \hat{\mathbf{z}}$                                                                                                                               | (4c)                | Ag I         |
| $\mathbf{B}_2$    | $= -\left(x_1 - \frac{1}{2}\right) \mathbf{a}_1 - \left(x_1 - \frac{1}{2}\right) \mathbf{a}_2 - \left(x_1 - \frac{1}{2}\right) \mathbf{a}_3$ | $=$ | $-c\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{z}}$                                                                                                   | (4c)                | Ag I         |
| $\mathbf{B}_3$    | $= -x_1 \mathbf{a}_1 - x_1 \mathbf{a}_2 - x_1 \mathbf{a}_3$                                                                                  | $=$ | $-cx_1 \hat{\mathbf{z}}$                                                                                                                              | (4c)                | Ag I         |
| $\mathbf{B}_4$    | $= \left(x_1 + \frac{1}{2}\right) \mathbf{a}_1 + \left(x_1 + \frac{1}{2}\right) \mathbf{a}_2 + \left(x_1 + \frac{1}{2}\right) \mathbf{a}_3$  | $=$ | $c\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{z}}$                                                                                                    | (4c)                | Ag I         |
| $\mathbf{B}_5$    | $= x_2 \mathbf{a}_1 + x_2 \mathbf{a}_2 + x_2 \mathbf{a}_3$                                                                                   | $=$ | $cx_2 \hat{\mathbf{z}}$                                                                                                                               | (4c)                | Ru I         |
| $\mathbf{B}_6$    | $= -\left(x_2 - \frac{1}{2}\right) \mathbf{a}_1 - \left(x_2 - \frac{1}{2}\right) \mathbf{a}_2 - \left(x_2 - \frac{1}{2}\right) \mathbf{a}_3$ | $=$ | $-c\left(x_2 - \frac{1}{2}\right) \hat{\mathbf{z}}$                                                                                                   | (4c)                | Ru I         |
| $\mathbf{B}_7$    | $= -x_2 \mathbf{a}_1 - x_2 \mathbf{a}_2 - x_2 \mathbf{a}_3$                                                                                  | $=$ | $-cx_2 \hat{\mathbf{z}}$                                                                                                                              | (4c)                | Ru I         |
| $\mathbf{B}_8$    | $= \left(x_2 + \frac{1}{2}\right) \mathbf{a}_1 + \left(x_2 + \frac{1}{2}\right) \mathbf{a}_2 + \left(x_2 + \frac{1}{2}\right) \mathbf{a}_3$  | $=$ | $c\left(x_2 + \frac{1}{2}\right) \hat{\mathbf{z}}$                                                                                                    | (4c)                | Ru I         |
| $\mathbf{B}_9$    | $= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$                                                                                   | $=$ | $\frac{1}{2}a(x_3 - z_3) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_3 - 2y_3 + z_3) \hat{\mathbf{y}} + \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}}$  | (12f)               | O I          |
| $\mathbf{B}_{10}$ | $= z_3 \mathbf{a}_1 + x_3 \mathbf{a}_2 + y_3 \mathbf{a}_3$                                                                                   | $=$ | $-\frac{1}{2}a(y_3 - z_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(2x_3 - y_3 - z_3) \hat{\mathbf{y}} + \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}}$ | (12f)               | O I          |
| $\mathbf{B}_{11}$ | $= y_3 \mathbf{a}_1 + z_3 \mathbf{a}_2 + x_3 \mathbf{a}_3$                                                                                   | $=$ | $-\frac{1}{2}a(x_3 - y_3) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_3 + y_3 - 2z_3) \hat{\mathbf{y}} + \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}}$ | (12f)               | O I          |

$$\begin{aligned}
\mathbf{B}_{12} &= -\left(z_3 - \frac{1}{2}\right) \mathbf{a}_1 - \left(y_3 - \frac{1}{2}\right) \mathbf{a}_2 - \left(x_3 - \frac{1}{2}\right) \mathbf{a}_3 = \frac{1}{2}a(x_3 - z_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 - 2y_3 + z_3) \hat{\mathbf{y}} - \frac{1}{6}c(2x_3 + 2y_3 + 2z_3 - 3) \hat{\mathbf{z}} & (12f) & \text{O I} \\
\mathbf{B}_{13} &= -\left(y_3 - \frac{1}{2}\right) \mathbf{a}_1 - \left(x_3 - \frac{1}{2}\right) \mathbf{a}_2 - \left(z_3 - \frac{1}{2}\right) \mathbf{a}_3 = -\frac{1}{2}a(y_3 - z_3) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(2x_3 - y_3 - z_3) \hat{\mathbf{y}} - \frac{1}{6}c(2x_3 + 2y_3 + 2z_3 - 3) \hat{\mathbf{z}} & (12f) & \text{O I} \\
\mathbf{B}_{14} &= -\left(x_3 - \frac{1}{2}\right) \mathbf{a}_1 - \left(z_3 - \frac{1}{2}\right) \mathbf{a}_2 - \left(y_3 - \frac{1}{2}\right) \mathbf{a}_3 = -\frac{1}{2}a(x_3 - y_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 + y_3 - 2z_3) \hat{\mathbf{y}} - \frac{1}{6}c(2x_3 + 2y_3 + 2z_3 - 3) \hat{\mathbf{z}} & (12f) & \text{O I} \\
\mathbf{B}_{15} &= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3 = -\frac{1}{2}a(x_3 - z_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 - 2y_3 + z_3) \hat{\mathbf{y}} - \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}} & (12f) & \text{O I} \\
\mathbf{B}_{16} &= -z_3 \mathbf{a}_1 - x_3 \mathbf{a}_2 - y_3 \mathbf{a}_3 = \frac{1}{2}a(y_3 - z_3) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(2x_3 - y_3 - z_3) \hat{\mathbf{y}} - \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}} & (12f) & \text{O I} \\
\mathbf{B}_{17} &= -y_3 \mathbf{a}_1 - z_3 \mathbf{a}_2 - x_3 \mathbf{a}_3 = \frac{1}{2}a(x_3 - y_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 + y_3 - 2z_3) \hat{\mathbf{y}} - \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}} & (12f) & \text{O I} \\
\mathbf{B}_{18} &= \left(z_3 + \frac{1}{2}\right) \mathbf{a}_1 + \left(y_3 + \frac{1}{2}\right) \mathbf{a}_2 + \left(x_3 + \frac{1}{2}\right) \mathbf{a}_3 = -\frac{1}{2}a(x_3 - z_3) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_3 - 2y_3 + z_3) \hat{\mathbf{y}} + \frac{1}{6}c(2x_3 + 2y_3 + 2z_3 + 3) \hat{\mathbf{z}} & (12f) & \text{O I} \\
\mathbf{B}_{19} &= \left(y_3 + \frac{1}{2}\right) \mathbf{a}_1 + \left(x_3 + \frac{1}{2}\right) \mathbf{a}_2 + \left(z_3 + \frac{1}{2}\right) \mathbf{a}_3 = \frac{1}{2}a(y_3 - z_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(2x_3 - y_3 - z_3) \hat{\mathbf{y}} + \frac{1}{6}c(2x_3 + 2y_3 + 2z_3 + 3) \hat{\mathbf{z}} & (12f) & \text{O I} \\
\mathbf{B}_{20} &= \left(x_3 + \frac{1}{2}\right) \mathbf{a}_1 + \left(z_3 + \frac{1}{2}\right) \mathbf{a}_2 + \left(y_3 + \frac{1}{2}\right) \mathbf{a}_3 = \frac{1}{2}a(x_3 - y_3) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_3 + y_3 - 2z_3) \hat{\mathbf{y}} + \frac{1}{6}c(2x_3 + 2y_3 + 2z_3 + 3) \hat{\mathbf{z}} & (12f) & \text{O I}
\end{aligned}$$

## References

- [1] B. E. Prasad, S. Kanungo, M. Jansen, A. C. Komarek, B. Yan, P. Manuel, and C. Felser, *AgRuO<sub>3</sub>, a Strongly Exchange-Coupled Honeycomb Compound Lacking Long-Range Magnetic Order*, Chem. Eur. J. **23**, 4680–4686 (2017), doi:10.1002/chem.201606057.

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- [1] W. Schnelle, B. E. Prasad, C. Felser, M. Jansen, E. V. Komleva, S. V. Streltsov, I. I. Mazin, D. Khalyavin, P. Manuel, S. Pal, D. V. S. Muthu, A. K. Sood, E. S. Klyushina, B. Lake, J.-C. Orain, and H. Luetkens, *Magnetic and electronic ordering phenomena in the Ru<sub>2</sub>O<sub>6</sub>-layer honeycomb lattice compound AgRuO<sub>3</sub>*, Phys. Rev. B **103**, 214413 (2021), doi:10.1103/PhysRevB.103.214413.

## First cited in

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