

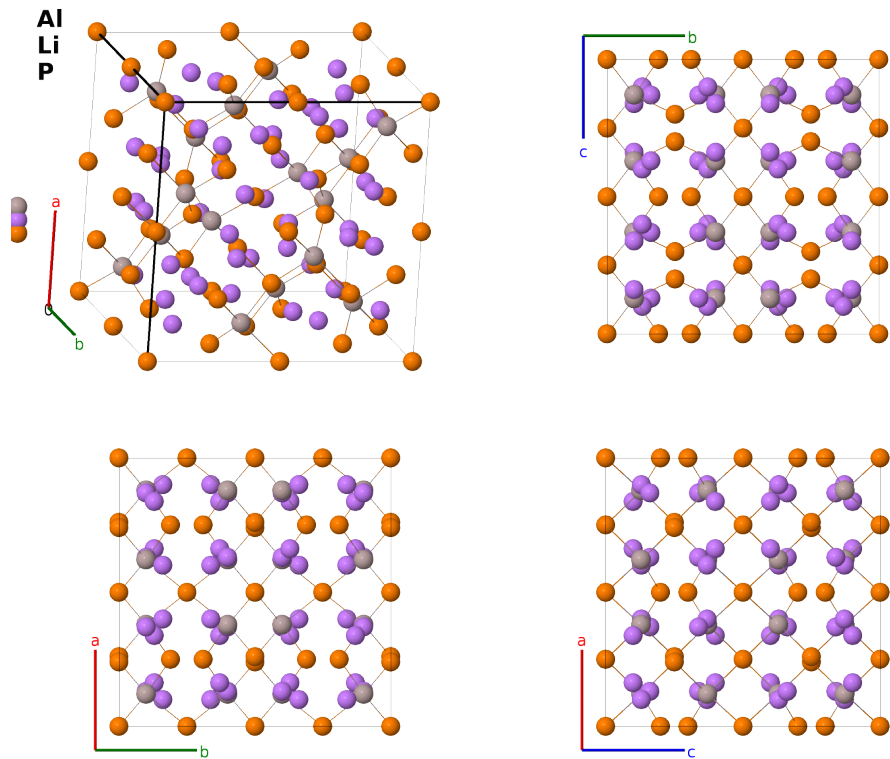
Predicted Li_3AlP_2 Structure: AB3C2_oI96_73_f_3f_acde-001

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<https://aflow.org/prototype-encyclopedia/QKN5>

https://aflow.org/prototype-encyclopedia/AB3C2_oI96_73_f_3f_acde-001



Prototype	AlLi_3P_2
AFLOW prototype label	AB3C2_oI96_73_f_3f_acde-001
ICSD	186820
CCDC	1695976
Pearson symbol	oI96
Space group number	73
Space group symbol	$Ibca$
AFLOW prototype command	<code>aflow --proto=AB3C2_oI96_73_f_3f_acde-001</code> <code>--params=a, b/a, c/a, x₂, y₃, z₄, x₅, y₅, z₅, x₆, y₆, z₆, x₇, y₇, z₇, x₈, y₈, z₈</code>

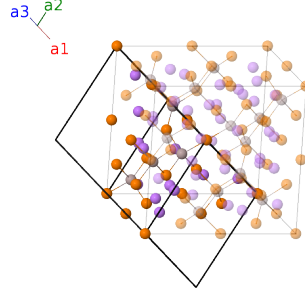
Other compounds with this structure

Li_3AlAs_2 , Li_3Ga_2

- The first experimental information we have for this structure is from (Juza, 1952), who placed the system in space group *Ibca* #71 but could not locate the lithium atoms, except to note that they are on a (16f) site.
- (Dadsetani, 2011) used this work as the starting point for first-principles calculations to minimize the total energy of the structure, including the positions of the lithium atoms, keeping the structure in space group *Ibca*, shown here.
- (Restle, 2020) used ball milling and annealing to produce samples of Li_3AlP_2 and Li_3GaP_2 and found them to be in space group *Cmce* #64. While we believe that this work is correct, we present both structures.
- (Dadsetani, 2011) only gave one (16f) position for the lithium atoms, so we generated the other two sets by taking $x \rightarrow y \rightarrow z \rightarrow x$.
- ICSD entry 186820 is no longer in the database. This suggests that this structure was withdrawn, but we have no confirmation of that.

Body-centered Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= -\frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}b\hat{\mathbf{y}} + \frac{1}{2}c\hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a\hat{\mathbf{x}} - \frac{1}{2}b\hat{\mathbf{y}} + \frac{1}{2}c\hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}b\hat{\mathbf{y}} - \frac{1}{2}c\hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= 0$	$=$	0	(8a)	P I
$\mathbf{B}_2$	$= \frac{1}{2}\mathbf{a}_1 + \frac{1}{2}\mathbf{a}_3$	$=$	$\frac{1}{2}b\hat{\mathbf{y}}$	(8a)	P I
$\mathbf{B}_3$	$= \frac{1}{2}\mathbf{a}_2 + \frac{1}{2}\mathbf{a}_3$	$=$	$\frac{1}{2}a\hat{\mathbf{x}}$	(8a)	P I
$\mathbf{B}_4$	$= \frac{1}{2}\mathbf{a}_1 + \frac{1}{2}\mathbf{a}_2$	$=$	$\frac{1}{2}c\hat{\mathbf{z}}$	(8a)	P I
$\mathbf{B}_5$	$= \frac{1}{4}\mathbf{a}_1 + (x_2 + \frac{1}{4})\mathbf{a}_2 + x_2\mathbf{a}_3$	$=$	$ax_2\hat{\mathbf{x}} + \frac{1}{4}c\hat{\mathbf{z}}$	(8c)	P II
$\mathbf{B}_6$	$= \frac{3}{4}\mathbf{a}_1 - (x_2 - \frac{1}{4})\mathbf{a}_2 - (x_2 - \frac{1}{2})\mathbf{a}_3$	$=$	$-ax_2\hat{\mathbf{x}} + \frac{1}{2}b\hat{\mathbf{y}} + \frac{1}{4}c\hat{\mathbf{z}}$	(8c)	P II
$\mathbf{B}_7$	$= \frac{3}{4}\mathbf{a}_1 - (x_2 - \frac{3}{4})\mathbf{a}_2 - x_2\mathbf{a}_3$	$=$	$-ax_2\hat{\mathbf{x}} + \frac{3}{4}c\hat{\mathbf{z}}$	(8c)	P II
$\mathbf{B}_8$	$= \frac{1}{4}\mathbf{a}_1 + (x_2 + \frac{3}{4})\mathbf{a}_2 + (x_2 + \frac{1}{2})\mathbf{a}_3$	$=$	$a(x_2 + \frac{1}{2})\hat{\mathbf{x}} + \frac{1}{4}c\hat{\mathbf{z}}$	(8c)	P II
$\mathbf{B}_9$	$= y_3\mathbf{a}_1 + \frac{1}{4}\mathbf{a}_2 + (y_3 + \frac{1}{4})\mathbf{a}_3$	$=$	$\frac{1}{4}a\hat{\mathbf{x}} + by_3\hat{\mathbf{y}}$	(8d)	P III
$\mathbf{B}_{10}$	$= -(y_3 - \frac{1}{2})\mathbf{a}_1 + \frac{3}{4}\mathbf{a}_2 - (y_3 - \frac{1}{4})\mathbf{a}_3$	$=$	$\frac{1}{4}a\hat{\mathbf{x}} - by_3\hat{\mathbf{y}} + \frac{1}{2}c\hat{\mathbf{z}}$	(8d)	P III
$\mathbf{B}_{11}$	$= -y_3\mathbf{a}_1 + \frac{3}{4}\mathbf{a}_2 - (y_3 - \frac{3}{4})\mathbf{a}_3$	$=$	$\frac{3}{4}a\hat{\mathbf{x}} - by_3\hat{\mathbf{y}}$	(8d)	P III
$\mathbf{B}_{12}$	$= (y_3 + \frac{1}{2})\mathbf{a}_1 + \frac{1}{4}\mathbf{a}_2 + (y_3 + \frac{3}{4})\mathbf{a}_3$	$=$	$\frac{1}{4}a\hat{\mathbf{x}} + b(y_3 + \frac{1}{2})\hat{\mathbf{y}}$	(8d)	P III
$\mathbf{B}_{13}$	$= (z_4 + \frac{1}{4})\mathbf{a}_1 + z_4\mathbf{a}_2 + \frac{1}{4}\mathbf{a}_3$	$=$	$\frac{1}{4}b\hat{\mathbf{y}} + cz_4\hat{\mathbf{z}}$	(8e)	P IV
$\mathbf{B}_{14}$	$= -(z_4 - \frac{1}{4})\mathbf{a}_1 - (z_4 - \frac{1}{2})\mathbf{a}_2 + \frac{3}{4}\mathbf{a}_3$	$=$	$\frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{4}b\hat{\mathbf{y}} - cz_4\hat{\mathbf{z}}$	(8e)	P IV
$\mathbf{B}_{15}$	$= -(z_4 - \frac{3}{4})\mathbf{a}_1 - z_4\mathbf{a}_2 + \frac{3}{4}\mathbf{a}_3$	$=$	$\frac{3}{4}b\hat{\mathbf{y}} - cz_4\hat{\mathbf{z}}$	(8e)	P IV
$\mathbf{B}_{16}$	$= (z_4 + \frac{3}{4})\mathbf{a}_1 + (z_4 + \frac{1}{2})\mathbf{a}_2 + \frac{1}{4}\mathbf{a}_3$	$=$	$\frac{1}{4}b\hat{\mathbf{y}} + c(z_4 + \frac{1}{2})\hat{\mathbf{z}}$	(8e)	P IV

$$\begin{aligned}
\mathbf{B}_{17} &= \begin{pmatrix} (y_5 + z_5) \mathbf{a}_1 + (x_5 + z_5) \mathbf{a}_2 + \\ (x_5 + y_5) \mathbf{a}_3 \end{pmatrix} = ax_5 \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{18} &= \begin{pmatrix} (-y_5 + z_5 + \frac{1}{2}) \mathbf{a}_1 - \\ (x_5 - z_5) \mathbf{a}_2 - (x_5 + y_5 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -ax_5 \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{19} &= \begin{pmatrix} (y_5 - z_5) \mathbf{a}_1 - (x_5 + z_5 - \frac{1}{2}) \mathbf{a}_2 + \\ (-x_5 + y_5 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(x_5 - \frac{1}{2}) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{20} &= \begin{pmatrix} -(y_5 + z_5 - \frac{1}{2}) \mathbf{a}_1 + \\ (x_5 - z_5 + \frac{1}{2}) \mathbf{a}_2 + (x_5 - y_5) \mathbf{a}_3 \end{pmatrix} = ax_5 \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{21} &= \begin{pmatrix} -(y_5 + z_5) \mathbf{a}_1 - (x_5 + z_5) \mathbf{a}_2 - \\ (x_5 + y_5) \mathbf{a}_3 \end{pmatrix} = -ax_5 \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{22} &= \begin{pmatrix} (y_5 - z_5 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_5 - z_5) \mathbf{a}_2 + (x_5 + y_5 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = ax_5 \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{23} &= \begin{pmatrix} -(y_5 - z_5) \mathbf{a}_1 + \\ (x_5 + z_5 + \frac{1}{2}) \mathbf{a}_2 + \\ (x_5 - y_5 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(x_5 + \frac{1}{2}) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{24} &= \begin{pmatrix} (y_5 + z_5 + \frac{1}{2}) \mathbf{a}_1 + \\ (-x_5 + z_5 + \frac{1}{2}) \mathbf{a}_2 - (x_5 - y_5) \mathbf{a}_3 \end{pmatrix} = -ax_5 \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{25} &= \begin{pmatrix} (y_6 + z_6) \mathbf{a}_1 + (x_6 + z_6) \mathbf{a}_2 + \\ (x_6 + y_6) \mathbf{a}_3 \end{pmatrix} = ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{26} &= \begin{pmatrix} (-y_6 + z_6 + \frac{1}{2}) \mathbf{a}_1 - \\ (x_6 - z_6) \mathbf{a}_2 - (x_6 + y_6 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -ax_6 \hat{\mathbf{x}} - b(y_6 - \frac{1}{2}) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{27} &= \begin{pmatrix} (y_6 - z_6) \mathbf{a}_1 - (x_6 + z_6 - \frac{1}{2}) \mathbf{a}_2 + \\ (-x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(x_6 - \frac{1}{2}) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{28} &= \begin{pmatrix} -(y_6 + z_6 - \frac{1}{2}) \mathbf{a}_1 + \\ (x_6 - z_6 + \frac{1}{2}) \mathbf{a}_2 + (x_6 - y_6) \mathbf{a}_3 \end{pmatrix} = ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{29} &= \begin{pmatrix} -(y_6 + z_6) \mathbf{a}_1 - (x_6 + z_6) \mathbf{a}_2 - \\ (x_6 + y_6) \mathbf{a}_3 \end{pmatrix} = -ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{30} &= \begin{pmatrix} (y_6 - z_6 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_6 - z_6) \mathbf{a}_2 + (x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = ax_6 \hat{\mathbf{x}} + b(y_6 + \frac{1}{2}) \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{31} &= \begin{pmatrix} -(y_6 - z_6) \mathbf{a}_1 + \\ (x_6 + z_6 + \frac{1}{2}) \mathbf{a}_2 + \\ (x_6 - y_6 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(x_6 + \frac{1}{2}) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{32} &= \begin{pmatrix} (y_6 + z_6 + \frac{1}{2}) \mathbf{a}_1 + \\ (-x_6 + z_6 + \frac{1}{2}) \mathbf{a}_2 - (x_6 - y_6) \mathbf{a}_3 \end{pmatrix} = -ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{33} &= \begin{pmatrix} (y_7 + z_7) \mathbf{a}_1 + (x_7 + z_7) \mathbf{a}_2 + \\ (x_7 + y_7) \mathbf{a}_3 \end{pmatrix} = ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{34} &= \begin{pmatrix} (-y_7 + z_7 + \frac{1}{2}) \mathbf{a}_1 - \\ (x_7 - z_7) \mathbf{a}_2 - (x_7 + y_7 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -ax_7 \hat{\mathbf{x}} - b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{35} &= \begin{pmatrix} (y_7 - z_7) \mathbf{a}_1 - (x_7 + z_7 - \frac{1}{2}) \mathbf{a}_2 + \\ (-x_7 + y_7 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(x_7 - \frac{1}{2}) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{36} &= \begin{pmatrix} -(y_7 + z_7 - \frac{1}{2}) \mathbf{a}_1 + \\ (x_7 - z_7 + \frac{1}{2}) \mathbf{a}_2 + (x_7 - y_7) \mathbf{a}_3 \end{pmatrix} = ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - c(z_7 - \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{37} &= \begin{pmatrix} -(y_7 + z_7) \mathbf{a}_1 - (x_7 + z_7) \mathbf{a}_2 - \\ (x_7 + y_7) \mathbf{a}_3 \end{pmatrix} = -ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{38} &= \begin{pmatrix} (y_7 - z_7 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_7 - z_7) \mathbf{a}_2 + (x_7 + y_7 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = ax_7 \hat{\mathbf{x}} + b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II}
\end{aligned}$$

$$\begin{aligned}
\mathbf{B}_{39} &= \begin{aligned} &-(y_7 - z_7) \mathbf{a}_1 + \\ &(x_7 + z_7 + \frac{1}{2}) \mathbf{a}_2 + \\ &(x_7 - y_7 + \frac{1}{2}) \mathbf{a}_3 \end{aligned} &= &a(x_7 + \frac{1}{2}) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} &(16f) &\text{Li II} \\
\mathbf{B}_{40} &= \begin{aligned} &(y_7 + z_7 + \frac{1}{2}) \mathbf{a}_1 + \\ &(-x_7 + z_7 + \frac{1}{2}) \mathbf{a}_2 - (x_7 - y_7) \mathbf{a}_3 \end{aligned} &= &-ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \hat{\mathbf{z}} &(16f) &\text{Li II} \\
\mathbf{B}_{41} &= \begin{aligned} &(y_8 + z_8) \mathbf{a}_1 + (x_8 + z_8) \mathbf{a}_2 + \\ &(x_8 + y_8) \mathbf{a}_3 \end{aligned} &= &ax_8 \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} &(16f) &\text{Li III} \\
\mathbf{B}_{42} &= \begin{aligned} &(-y_8 + z_8 + \frac{1}{2}) \mathbf{a}_1 - \\ &(x_8 - z_8) \mathbf{a}_2 - (x_8 + y_8 - \frac{1}{2}) \mathbf{a}_3 \end{aligned} &= &-ax_8 \hat{\mathbf{x}} - b(y_8 - \frac{1}{2}) \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} &(16f) &\text{Li III} \\
\mathbf{B}_{43} &= \begin{aligned} &(y_8 - z_8) \mathbf{a}_1 - (x_8 + z_8 - \frac{1}{2}) \mathbf{a}_2 + \\ &(-x_8 + y_8 + \frac{1}{2}) \mathbf{a}_3 \end{aligned} &= &-a(x_8 - \frac{1}{2}) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} - cz_8 \hat{\mathbf{z}} &(16f) &\text{Li III} \\
\mathbf{B}_{44} &= \begin{aligned} &-(y_8 + z_8 - \frac{1}{2}) \mathbf{a}_1 + \\ &(x_8 - z_8 + \frac{1}{2}) \mathbf{a}_2 + (x_8 - y_8) \mathbf{a}_3 \end{aligned} &= &ax_8 \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - c(z_8 - \frac{1}{2}) \hat{\mathbf{z}} &(16f) &\text{Li III} \\
\mathbf{B}_{45} &= \begin{aligned} &-(y_8 + z_8) \mathbf{a}_1 - (x_8 + z_8) \mathbf{a}_2 - \\ &(x_8 + y_8) \mathbf{a}_3 \end{aligned} &= &-ax_8 \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \hat{\mathbf{z}} &(16f) &\text{Li III} \\
\mathbf{B}_{46} &= \begin{aligned} &(y_8 - z_8 + \frac{1}{2}) \mathbf{a}_1 + \\ &(x_8 - z_8) \mathbf{a}_2 + (x_8 + y_8 + \frac{1}{2}) \mathbf{a}_3 \end{aligned} &= &ax_8 \hat{\mathbf{x}} + b(y_8 + \frac{1}{2}) \hat{\mathbf{y}} - cz_8 \hat{\mathbf{z}} &(16f) &\text{Li III} \\
\mathbf{B}_{47} &= \begin{aligned} &-(y_8 - z_8) \mathbf{a}_1 + \\ &(x_8 + z_8 + \frac{1}{2}) \mathbf{a}_2 + \\ &(x_8 - y_8 + \frac{1}{2}) \mathbf{a}_3 \end{aligned} &= &a(x_8 + \frac{1}{2}) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} &(16f) &\text{Li III} \\
\mathbf{B}_{48} &= \begin{aligned} &(y_8 + z_8 + \frac{1}{2}) \mathbf{a}_1 + \\ &(-x_8 + z_8 + \frac{1}{2}) \mathbf{a}_2 - (x_8 - y_8) \mathbf{a}_3 \end{aligned} &= &-ax_8 \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \hat{\mathbf{z}} &(16f) &\text{Li III}
\end{aligned}$$

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