

Rb₃AsSe₁₆ Structure: AB3C16_cF160_203_a_bc_eg-001

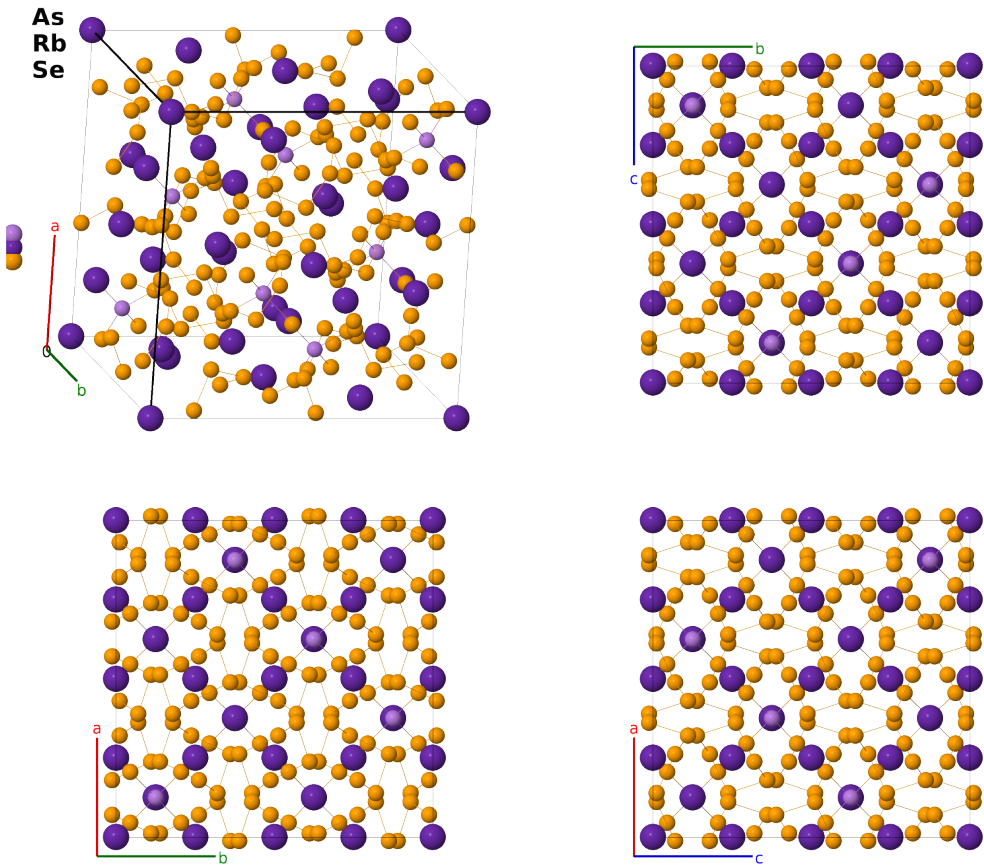
This structure previously used the label(s) **AB3C16_cF160_203_a_bc_eg**. Calls to these addresses will be redirected here.

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<https://aflow.org/prototype-encyclopedia/HAGZ>

https://aflow.org/prototype-encyclopedia/AB3C16_cF160_203_a_bc_eg-001

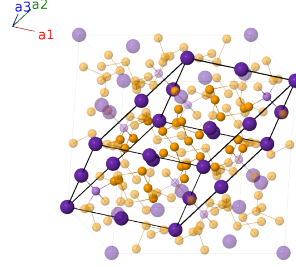


Prototype	AsRb ₃ Se ₁₆
AFLOW prototype label	AB3C16_cF160_203_a_bc_eg-001
ICSD	405959
CCDC	1725267
Pearson symbol	cF160
Space group number	203
Space group symbol	$Fd\bar{3}$

AFLOW prototype command aflow --proto=AB3C16_cF160_203_a_bc_eg-001
 --params= a, x_4, x_5, y_5, z_5

Face-centered Cubic primitive vectors

$$\begin{aligned} \mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}} \end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= \frac{1}{8} \mathbf{a}_1 + \frac{1}{8} \mathbf{a}_2 + \frac{1}{8} \mathbf{a}_3$	$=$	$\frac{1}{8}a \hat{\mathbf{x}} + \frac{1}{8}a \hat{\mathbf{y}} + \frac{1}{8}a \hat{\mathbf{z}}$	(8a)	As I
$\mathbf{B}_2$	$= \frac{7}{8} \mathbf{a}_1 + \frac{7}{8} \mathbf{a}_2 + \frac{7}{8} \mathbf{a}_3$	$=$	$\frac{7}{8}a \hat{\mathbf{x}} + \frac{7}{8}a \hat{\mathbf{y}} + \frac{7}{8}a \hat{\mathbf{z}}$	(8a)	As I
$\mathbf{B}_3$	$= \frac{5}{8} \mathbf{a}_1 + \frac{5}{8} \mathbf{a}_2 + \frac{5}{8} \mathbf{a}_3$	$=$	$\frac{5}{8}a \hat{\mathbf{x}} + \frac{5}{8}a \hat{\mathbf{y}} + \frac{5}{8}a \hat{\mathbf{z}}$	(8b)	Rb I
$\mathbf{B}_4$	$= \frac{3}{8} \mathbf{a}_1 + \frac{3}{8} \mathbf{a}_2 + \frac{3}{8} \mathbf{a}_3$	$=$	$\frac{3}{8}a \hat{\mathbf{x}} + \frac{3}{8}a \hat{\mathbf{y}} + \frac{3}{8}a \hat{\mathbf{z}}$	(8b)	Rb I
$\mathbf{B}_5$	$= 0$	$=$	0	(16c)	Rb II
$\mathbf{B}_6$	$= \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + \frac{1}{4}a \hat{\mathbf{y}}$	(16c)	Rb II
$\mathbf{B}_7$	$= \frac{1}{2} \mathbf{a}_2$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + \frac{1}{4}a \hat{\mathbf{z}}$	(16c)	Rb II
$\mathbf{B}_8$	$= \frac{1}{2} \mathbf{a}_1$	$=$	$\frac{1}{4}a \hat{\mathbf{y}} + \frac{1}{4}a \hat{\mathbf{z}}$	(16c)	Rb II
$\mathbf{B}_9$	$= x_4 \mathbf{a}_1 + x_4 \mathbf{a}_2 + x_4 \mathbf{a}_3$	$=$	$ax_4 \hat{\mathbf{x}} + ax_4 \hat{\mathbf{y}} + ax_4 \hat{\mathbf{z}}$	(32e)	Se I
$\mathbf{B}_{10}$	$= x_4 \mathbf{a}_1 + x_4 \mathbf{a}_2 - \left(3x_4 - \frac{1}{2}\right) \mathbf{a}_3$	$=$	$-a \left(x_4 - \frac{1}{4}\right) \hat{\mathbf{x}} - a \left(x_4 - \frac{1}{4}\right) \hat{\mathbf{y}} + ax_4 \hat{\mathbf{z}}$	(32e)	Se I
$\mathbf{B}_{11}$	$= x_4 \mathbf{a}_1 - \left(3x_4 - \frac{1}{2}\right) \mathbf{a}_2 + x_4 \mathbf{a}_3$	$=$	$-a \left(x_4 - \frac{1}{4}\right) \hat{\mathbf{x}} + ax_4 \hat{\mathbf{y}} - a \left(x_4 - \frac{1}{4}\right) \hat{\mathbf{z}}$	(32e)	Se I
$\mathbf{B}_{12}$	$= -\left(3x_4 - \frac{1}{2}\right) \mathbf{a}_1 + x_4 \mathbf{a}_2 + x_4 \mathbf{a}_3$	$=$	$ax_4 \hat{\mathbf{x}} - a \left(x_4 - \frac{1}{4}\right) \hat{\mathbf{y}} - a \left(x_4 - \frac{1}{4}\right) \hat{\mathbf{z}}$	(32e)	Se I
$\mathbf{B}_{13}$	$= -x_4 \mathbf{a}_1 - x_4 \mathbf{a}_2 - x_4 \mathbf{a}_3$	$=$	$-ax_4 \hat{\mathbf{x}} - ax_4 \hat{\mathbf{y}} - ax_4 \hat{\mathbf{z}}$	(32e)	Se I
$\mathbf{B}_{14}$	$= -x_4 \mathbf{a}_1 - x_4 \mathbf{a}_2 + \left(3x_4 + \frac{1}{2}\right) \mathbf{a}_3$	$=$	$a \left(x_4 + \frac{1}{4}\right) \hat{\mathbf{x}} + a \left(x_4 + \frac{1}{4}\right) \hat{\mathbf{y}} - ax_4 \hat{\mathbf{z}}$	(32e)	Se I
$\mathbf{B}_{15}$	$= -x_4 \mathbf{a}_1 + \left(3x_4 + \frac{1}{2}\right) \mathbf{a}_2 - x_4 \mathbf{a}_3$	$=$	$a \left(x_4 + \frac{1}{4}\right) \hat{\mathbf{x}} - ax_4 \hat{\mathbf{y}} + a \left(x_4 + \frac{1}{4}\right) \hat{\mathbf{z}}$	(32e)	Se I
$\mathbf{B}_{16}$	$= \left(3x_4 + \frac{1}{2}\right) \mathbf{a}_1 - x_4 \mathbf{a}_2 - x_4 \mathbf{a}_3$	$=$	$-ax_4 \hat{\mathbf{x}} + a \left(x_4 + \frac{1}{4}\right) \hat{\mathbf{y}} + a \left(x_4 + \frac{1}{4}\right) \hat{\mathbf{z}}$	(32e)	Se I
$\mathbf{B}_{17}$	$= (-x_5 + y_5 + z_5) \mathbf{a}_1 +$ $(x_5 - y_5 + z_5) \mathbf{a}_2 +$ $(x_5 + y_5 - z_5) \mathbf{a}_3$	$=$	$ax_5 \hat{\mathbf{x}} + ay_5 \hat{\mathbf{y}} + az_5 \hat{\mathbf{z}}$	(96g)	Se II
$\mathbf{B}_{18}$	$= (x_5 - y_5 + z_5) \mathbf{a}_1 +$ $(-x_5 + y_5 + z_5) \mathbf{a}_2 -$ $(x_5 + y_5 + z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a \left(x_5 - \frac{1}{4}\right) \hat{\mathbf{x}} - a \left(y_5 - \frac{1}{4}\right) \hat{\mathbf{y}} + az_5 \hat{\mathbf{z}}$	(96g)	Se II
$\mathbf{B}_{19}$	$= (x_5 + y_5 - z_5) \mathbf{a}_1 -$ $(x_5 + y_5 + z_5 - \frac{1}{2}) \mathbf{a}_2 +$ $(-x_5 + y_5 + z_5) \mathbf{a}_3$	$=$	$-a \left(x_5 - \frac{1}{4}\right) \hat{\mathbf{x}} + ay_5 \hat{\mathbf{y}} - a \left(z_5 - \frac{1}{4}\right) \hat{\mathbf{z}}$	(96g)	Se II
$\mathbf{B}_{20}$	$= -(x_5 + y_5 + z_5 - \frac{1}{2}) \mathbf{a}_1 +$ $(x_5 + y_5 - z_5) \mathbf{a}_2 +$ $(x_5 - y_5 + z_5) \mathbf{a}_3$	$=$	$ax_5 \hat{\mathbf{x}} - a \left(y_5 - \frac{1}{4}\right) \hat{\mathbf{y}} - a \left(z_5 - \frac{1}{4}\right) \hat{\mathbf{z}}$	(96g)	Se II

$\mathbf{B}_{21} =$	$(x_5 + y_5 - z_5) \mathbf{a}_1 +$ $(-x_5 + y_5 + z_5) \mathbf{a}_2 +$ $(x_5 - y_5 + z_5) \mathbf{a}_3$	$=$	$az_5 \hat{\mathbf{x}} + ax_5 \hat{\mathbf{y}} + ay_5 \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{22} =$	$-(x_5 + y_5 + z_5 - \frac{1}{2}) \mathbf{a}_1 +$ $(x_5 - y_5 + z_5) \mathbf{a}_2 +$ $(-x_5 + y_5 + z_5) \mathbf{a}_3$	$=$	$az_5 \hat{\mathbf{x}} - a(x_5 - \frac{1}{4}) \hat{\mathbf{y}} - a(y_5 - \frac{1}{4}) \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{23} =$	$(-x_5 + y_5 + z_5) \mathbf{a}_1 +$ $(x_5 + y_5 - z_5) \mathbf{a}_2 -$ $(x_5 + y_5 + z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(z_5 - \frac{1}{4}) \hat{\mathbf{x}} - a(x_5 - \frac{1}{4}) \hat{\mathbf{y}} + ay_5 \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{24} =$	$(x_5 - y_5 + z_5) \mathbf{a}_1 -$ $(x_5 + y_5 + z_5 - \frac{1}{2}) \mathbf{a}_2 +$ $(x_5 + y_5 - z_5) \mathbf{a}_3$	$=$	$-a(z_5 - \frac{1}{4}) \hat{\mathbf{x}} + ax_5 \hat{\mathbf{y}} - a(y_5 - \frac{1}{4}) \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{25} =$	$(x_5 - y_5 + z_5) \mathbf{a}_1 +$ $(x_5 + y_5 - z_5) \mathbf{a}_2 +$ $(-x_5 + y_5 + z_5) \mathbf{a}_3$	$=$	$ay_5 \hat{\mathbf{x}} + az_5 \hat{\mathbf{y}} + ax_5 \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{26} =$	$(-x_5 + y_5 + z_5) \mathbf{a}_1 -$ $(x_5 + y_5 + z_5 - \frac{1}{2}) \mathbf{a}_2 +$ $(x_5 - y_5 + z_5) \mathbf{a}_3$	$=$	$-a(y_5 - \frac{1}{4}) \hat{\mathbf{x}} + az_5 \hat{\mathbf{y}} - a(x_5 - \frac{1}{4}) \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{27} =$	$-(x_5 + y_5 + z_5 - \frac{1}{2}) \mathbf{a}_1 +$ $(-x_5 + y_5 + z_5) \mathbf{a}_2 +$ $(x_5 + y_5 - z_5) \mathbf{a}_3$	$=$	$ay_5 \hat{\mathbf{x}} - a(z_5 - \frac{1}{4}) \hat{\mathbf{y}} - a(x_5 - \frac{1}{4}) \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{28} =$	$(x_5 + y_5 - z_5) \mathbf{a}_1 +$ $(x_5 - y_5 + z_5) \mathbf{a}_2 -$ $(x_5 + y_5 + z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(y_5 - \frac{1}{4}) \hat{\mathbf{x}} - a(z_5 - \frac{1}{4}) \hat{\mathbf{y}} + ax_5 \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{29} =$	$(x_5 - y_5 - z_5) \mathbf{a}_1 -$ $(x_5 - y_5 + z_5) \mathbf{a}_2 -$ $(x_5 + y_5 - z_5) \mathbf{a}_3$	$=$	$-ax_5 \hat{\mathbf{x}} - ay_5 \hat{\mathbf{y}} - az_5 \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{30} =$	$-(x_5 - y_5 + z_5) \mathbf{a}_1 +$ $(x_5 - y_5 - z_5) \mathbf{a}_2 +$ $(x_5 + y_5 + z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$a(x_5 + \frac{1}{4}) \hat{\mathbf{x}} + a(y_5 + \frac{1}{4}) \hat{\mathbf{y}} - az_5 \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{31} =$	$-(x_5 + y_5 - z_5) \mathbf{a}_1 +$ $(x_5 + y_5 + z_5 + \frac{1}{2}) \mathbf{a}_2 +$ $(x_5 - y_5 - z_5) \mathbf{a}_3$	$=$	$a(x_5 + \frac{1}{4}) \hat{\mathbf{x}} - ay_5 \hat{\mathbf{y}} + a(z_5 + \frac{1}{4}) \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{32} =$	$(x_5 + y_5 + z_5 + \frac{1}{2}) \mathbf{a}_1 -$ $(x_5 + y_5 - z_5) \mathbf{a}_2 -$ $(x_5 - y_5 + z_5) \mathbf{a}_3$	$=$	$-ax_5 \hat{\mathbf{x}} + a(y_5 + \frac{1}{4}) \hat{\mathbf{y}} + a(z_5 + \frac{1}{4}) \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{33} =$	$-(x_5 + y_5 - z_5) \mathbf{a}_1 +$ $(x_5 - y_5 - z_5) \mathbf{a}_2 -$ $(x_5 - y_5 + z_5) \mathbf{a}_3$	$=$	$-az_5 \hat{\mathbf{x}} - ax_5 \hat{\mathbf{y}} - ay_5 \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{34} =$	$(x_5 + y_5 + z_5 + \frac{1}{2}) \mathbf{a}_1 -$ $(x_5 - y_5 + z_5) \mathbf{a}_2 +$ $(x_5 - y_5 - z_5) \mathbf{a}_3$	$=$	$-az_5 \hat{\mathbf{x}} + a(x_5 + \frac{1}{4}) \hat{\mathbf{y}} + a(y_5 + \frac{1}{4}) \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{35} =$	$(x_5 - y_5 - z_5) \mathbf{a}_1 -$ $(x_5 + y_5 - z_5) \mathbf{a}_2 +$ $(x_5 + y_5 + z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$a(z_5 + \frac{1}{4}) \hat{\mathbf{x}} + a(x_5 + \frac{1}{4}) \hat{\mathbf{y}} - ay_5 \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{36} =$	$-(x_5 - y_5 + z_5) \mathbf{a}_1 +$ $(x_5 + y_5 + z_5 + \frac{1}{2}) \mathbf{a}_2 -$ $(x_5 + y_5 - z_5) \mathbf{a}_3$	$=$	$a(z_5 + \frac{1}{4}) \hat{\mathbf{x}} - ax_5 \hat{\mathbf{y}} + a(y_5 + \frac{1}{4}) \hat{\mathbf{z}}$	$(96g)$	Se II
$\mathbf{B}_{37} =$	$-(x_5 - y_5 + z_5) \mathbf{a}_1 -$ $(x_5 + y_5 - z_5) \mathbf{a}_2 +$ $(x_5 - y_5 - z_5) \mathbf{a}_3$	$=$	$-ay_5 \hat{\mathbf{x}} - az_5 \hat{\mathbf{y}} - ax_5 \hat{\mathbf{z}}$	$(96g)$	Se II

$$\begin{aligned}
\mathbf{B}_{38} &= \begin{pmatrix} x_5 - y_5 - z_5 \\ x_5 + y_5 + z_5 + \frac{1}{2} \\ x_5 - y_5 + z_5 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_5 - y_5 - z_5 \\ x_5 + y_5 + z_5 + \frac{1}{2} \\ x_5 - y_5 + z_5 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_5 - y_5 - z_5 \\ x_5 + y_5 + z_5 + \frac{1}{2} \\ x_5 - y_5 + z_5 \end{pmatrix} \mathbf{a}_3 &= a \left(y_5 + \frac{1}{4} \right) \hat{\mathbf{x}} - az_5 \hat{\mathbf{y}} + a \left(x_5 + \frac{1}{4} \right) \hat{\mathbf{z}} & (96g) & \text{Se II} \\
\mathbf{B}_{39} &= \begin{pmatrix} x_5 + y_5 + z_5 + \frac{1}{2} \\ x_5 - y_5 - z_5 \\ x_5 + y_5 - z_5 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_5 + y_5 + z_5 + \frac{1}{2} \\ x_5 - y_5 - z_5 \\ x_5 + y_5 - z_5 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_5 + y_5 + z_5 + \frac{1}{2} \\ x_5 - y_5 - z_5 \\ x_5 + y_5 - z_5 \end{pmatrix} \mathbf{a}_3 &= -ay_5 \hat{\mathbf{x}} + a \left(z_5 + \frac{1}{4} \right) \hat{\mathbf{y}} + a \left(x_5 + \frac{1}{4} \right) \hat{\mathbf{z}} & (96g) & \text{Se II} \\
\mathbf{B}_{40} &= \begin{pmatrix} x_5 + y_5 - z_5 \\ x_5 - y_5 + z_5 \\ x_5 + y_5 + z_5 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_5 + y_5 - z_5 \\ x_5 - y_5 + z_5 \\ x_5 + y_5 + z_5 + \frac{1}{2} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_5 + y_5 - z_5 \\ x_5 - y_5 + z_5 \\ x_5 + y_5 + z_5 + \frac{1}{2} \end{pmatrix} \mathbf{a}_3 &= a \left(y_5 + \frac{1}{4} \right) \hat{\mathbf{x}} + a \left(z_5 + \frac{1}{4} \right) \hat{\mathbf{y}} - ax_5 \hat{\mathbf{z}} & (96g) & \text{Se II}
\end{aligned}$$

References

- [1] M. Wachhold and W. S. Sheldrick, *Methanolothermale Synthese von $Rb_3AsSe_4 \cdot 2Se_6$ und $Cs_3AsSe_4 \cdot 2Cs_2As_2Se_4 \cdot 6Te_4Se_2$, zwei Selenidoarsenate mit sechsgliedrigen Chalkogenringen*, Z. Naturforsch. B **52**, 169–175 (1997), doi:10.1515/znb-1997-0204.

Found in

- [1] P. Villars and K. Cenzual, *Pearson's Crystal Data – Crystal Structure Database for Inorganic Compounds* (2013). ASM International.

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D. Hicks, M. J. Mehl, E. Gossett, C. Toher, O. Levy, R. M. Hanson, G. Hart, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 2*, Comput. Mater. Sci. **161**, S1 (2019). doi: 10.1016/j.commatsci.2018.10.043