

# Li<sub>7</sub>TaO<sub>6</sub> Structure:

## A8B6C\_hR15\_148\_cf\_f\_a-001

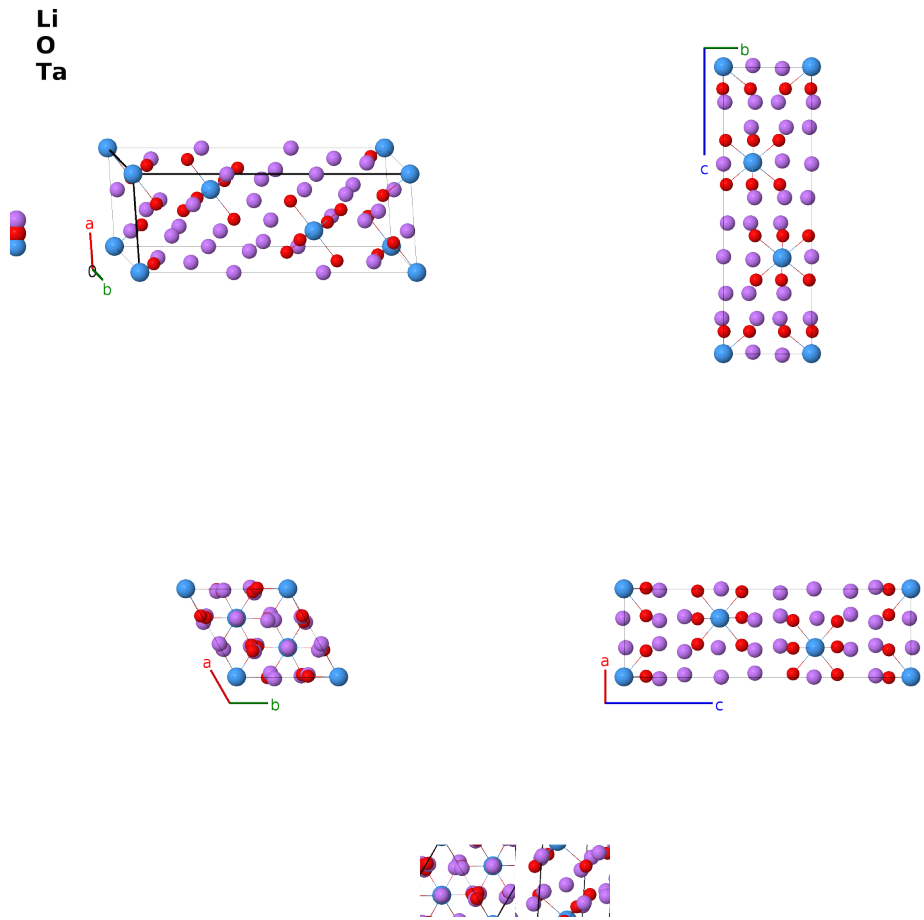
This structure previously used the label(s) **A8B6C\_hR15\_148\_cf\_f\_a**. Calls to these addresses will be redirected here.

Cite this page as:

- H. Eckert, S. Divilov, M. J. Mehl, D. Hicks, A. C. Zettl, M. Esters, X. Campilongo, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*, Comput. Mater. Sci. **240**, 112988 (2024), doi: 10.1016/j.commatsci.2024.112988.
- D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

<https://aflow.org/prototype-encyclopedia/L1GH>

[https://aflow.org/prototype-encyclopedia/A8B6C\\_hR15\\_148\\_cf\\_f\\_a-001](https://aflow.org/prototype-encyclopedia/A8B6C_hR15_148_cf_f_a-001)



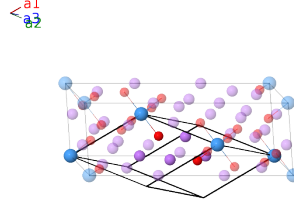
|                       |                                   |
|-----------------------|-----------------------------------|
| Prototype             | Li <sub>7</sub> O <sub>6</sub> Ta |
| AFLOW prototype label | A8B6C_hR15_148_cf_f_a-001         |
| ICSD                  | 74949                             |
| CCDC                  | 1635617                           |
| Pearson symbol        | hR15                              |
| Space group number    | 148                               |
| Space group symbol    | $R\bar{3}$                        |

AFLOW prototype command    `aflow --proto=A8B6C_hR15_148_cf_f_a-001`  
                                   `--params=a, c/a, x2, x3, y3, z3, x4, y4, z4`

- The Li-I (2c) site is half-occupied.

## Rhombohedral primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a \hat{\mathbf{y}} + \frac{1}{3}c \hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{\sqrt{3}}a \hat{\mathbf{y}} + \frac{1}{3}c \hat{\mathbf{z}} \\ \mathbf{a}_3 &= -\frac{1}{2}a \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a \hat{\mathbf{y}} + \frac{1}{3}c \hat{\mathbf{z}}\end{aligned}$$



## Basis vectors

|                   | Lattice<br>coordinates |                                                           | Cartesian<br>coordinates | Wyckoff<br>position                                                                                                                                   | Atom<br>type |
|-------------------|------------------------|-----------------------------------------------------------|--------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|
| $\mathbf{B}_1$    | $=$                    | $0$                                                       | $=$                      | $0$                                                                                                                                                   | Ta I         |
| $\mathbf{B}_2$    | $=$                    | $x_2 \mathbf{a}_1 + x_2 \mathbf{a}_2 + x_2 \mathbf{a}_3$  | $=$                      | $cx_2 \hat{\mathbf{z}}$                                                                                                                               | (2c) Li I    |
| $\mathbf{B}_3$    | $=$                    | $-x_2 \mathbf{a}_1 - x_2 \mathbf{a}_2 - x_2 \mathbf{a}_3$ | $=$                      | $-cx_2 \hat{\mathbf{z}}$                                                                                                                              | (2c) Li I    |
| $\mathbf{B}_4$    | $=$                    | $x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$  | $=$                      | $\frac{1}{2}a(x_3 - z_3) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_3 - 2y_3 + z_3) \hat{\mathbf{y}} + \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}}$  | (6f) Li II   |
| $\mathbf{B}_5$    | $=$                    | $z_3 \mathbf{a}_1 + x_3 \mathbf{a}_2 + y_3 \mathbf{a}_3$  | $=$                      | $-\frac{1}{2}a(y_3 - z_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(2x_3 - y_3 - z_3) \hat{\mathbf{y}} + \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}}$ | (6f) Li II   |
| $\mathbf{B}_6$    | $=$                    | $y_3 \mathbf{a}_1 + z_3 \mathbf{a}_2 + x_3 \mathbf{a}_3$  | $=$                      | $-\frac{1}{2}a(x_3 - y_3) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_3 + y_3 - 2z_3) \hat{\mathbf{y}} + \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}}$ | (6f) Li II   |
| $\mathbf{B}_7$    | $=$                    | $-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$ | $=$                      | $-\frac{1}{2}a(x_3 - z_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 - 2y_3 + z_3) \hat{\mathbf{y}} - \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}}$ | (6f) Li II   |
| $\mathbf{B}_8$    | $=$                    | $-z_3 \mathbf{a}_1 - x_3 \mathbf{a}_2 - y_3 \mathbf{a}_3$ | $=$                      | $\frac{1}{2}a(y_3 - z_3) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(2x_3 - y_3 - z_3) \hat{\mathbf{y}} - \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}}$  | (6f) Li II   |
| $\mathbf{B}_9$    | $=$                    | $-y_3 \mathbf{a}_1 - z_3 \mathbf{a}_2 - x_3 \mathbf{a}_3$ | $=$                      | $\frac{1}{2}a(x_3 - y_3) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 + y_3 - 2z_3) \hat{\mathbf{y}} - \frac{1}{3}c(x_3 + y_3 + z_3) \hat{\mathbf{z}}$  | (6f) Li II   |
| $\mathbf{B}_{10}$ | $=$                    | $x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$  | $=$                      | $\frac{1}{2}a(x_4 - z_4) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_4 - 2y_4 + z_4) \hat{\mathbf{y}} + \frac{1}{3}c(x_4 + y_4 + z_4) \hat{\mathbf{z}}$  | (6f) O I     |
| $\mathbf{B}_{11}$ | $=$                    | $z_4 \mathbf{a}_1 + x_4 \mathbf{a}_2 + y_4 \mathbf{a}_3$  | $=$                      | $-\frac{1}{2}a(y_4 - z_4) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(2x_4 - y_4 - z_4) \hat{\mathbf{y}} + \frac{1}{3}c(x_4 + y_4 + z_4) \hat{\mathbf{z}}$ | (6f) O I     |
| $\mathbf{B}_{12}$ | $=$                    | $y_4 \mathbf{a}_1 + z_4 \mathbf{a}_2 + x_4 \mathbf{a}_3$  | $=$                      | $-\frac{1}{2}a(x_4 - y_4) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_4 + y_4 - 2z_4) \hat{\mathbf{y}} + \frac{1}{3}c(x_4 + y_4 + z_4) \hat{\mathbf{z}}$ | (6f) O I     |
| $\mathbf{B}_{13}$ | $=$                    | $-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$ | $=$                      | $-\frac{1}{2}a(x_4 - z_4) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_4 - 2y_4 + z_4) \hat{\mathbf{y}} - \frac{1}{3}c(x_4 + y_4 + z_4) \hat{\mathbf{z}}$ | (6f) O I     |
| $\mathbf{B}_{14}$ | $=$                    | $-z_4 \mathbf{a}_1 - x_4 \mathbf{a}_2 - y_4 \mathbf{a}_3$ | $=$                      | $\frac{1}{2}a(y_4 - z_4) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(2x_4 - y_4 - z_4) \hat{\mathbf{y}} - \frac{1}{3}c(x_4 + y_4 + z_4) \hat{\mathbf{z}}$  | (6f) O I     |
| $\mathbf{B}_{15}$ | $=$                    | $-y_4 \mathbf{a}_1 - z_4 \mathbf{a}_2 - x_4 \mathbf{a}_3$ | $=$                      | $\frac{1}{2}a(x_4 - y_4) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_4 + y_4 - 2z_4) \hat{\mathbf{y}} - \frac{1}{3}c(x_4 + y_4 + z_4) \hat{\mathbf{z}}$  | (6f) O I     |

## References

- [1] G. Wehrum and R. Hoppe, *Zur Kenntnis ‘Kationen-reicher’ Tantalate Über  $\text{Li}_7[\text{TaO}_6]$* , Z. Anorganische und Allgemeine Chemie **620**, 659–664 (1994), doi:10.1002/zaac.19946200414.

## Found in

- [1] L. Kahle, X. Cheng, T. Binninger, S. D. Lacey, A. Marcolongo, F. Zipoli, E. Gilardi, C. Villevieille, M. E. Kazzi, N. Marzari, and D. Pergolesi, *The solid-state Li-ion conductor  $\text{Li}_7\text{TaO}_6$  : A combined computational and experimental study*, Solid State Ion. **347**, 115226 (2020), doi:10.1016/j.ssi.2020.115226.

## First cited in

D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.