

K₂NbF₇ (*K*6₂) Structure: A7B2C_mP40_14_7e_2e_e-001

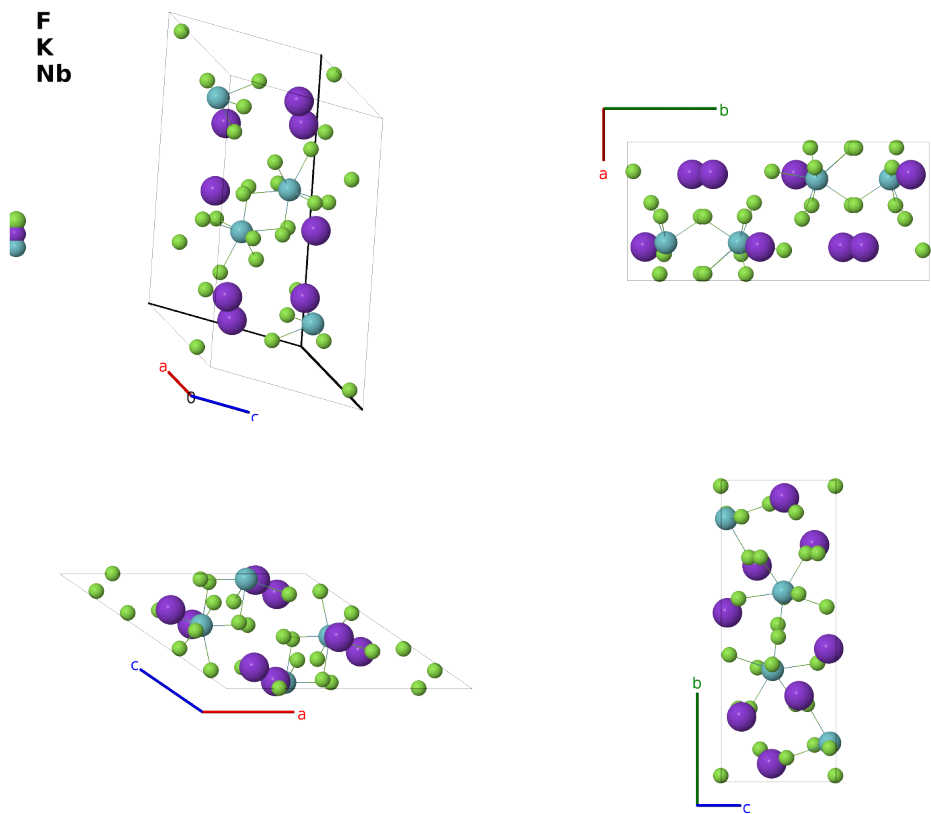
This structure previously used the label(s) **A7B2C_mP40_14_7e_2e_e**. Calls to these addresses will be redirected here.

Cite this page as:

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- D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

<https://aflow.org/prototype-encyclopedia/TF3J>

https://aflow.org/prototype-encyclopedia/A7B2C_mP40_14_7e_2e_e-001



Prototype	F ₇ K ₂ Nb
AFLOW prototype label	A7B2C_mP40_14_7e_2e_e-001
<i>Strukturbericht</i> designation	<i>K</i> 6 ₂
ICSD	14132
CCDC	1595533
Pearson symbol	mP40
Space group number	14
Space group symbol	<i>P</i> 2 ₁ / <i>c</i>

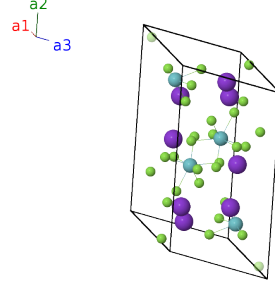
AFLOW prototype command `aflow --proto=A7B2C_mP40_14_7e_2e_e-001`
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Other compounds with this structure

K_2TaF_7

Simple Monoclinic primitive vectors

$$\begin{aligned} \mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}} \end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	$=$	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	F I
$\mathbf{B}_2$	$= -x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F I
$\mathbf{B}_3$	$= -x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	$=$	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	F I
$\mathbf{B}_4$	$= x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F I
$\mathbf{B}_5$	$= x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	F II
$\mathbf{B}_6$	$= -x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F II
$\mathbf{B}_7$	$= -x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	F II
$\mathbf{B}_8$	$= x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F II
$\mathbf{B}_9$	$= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	F III
$\mathbf{B}_{10}$	$= -x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F III
$\mathbf{B}_{11}$	$= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	F III
$\mathbf{B}_{12}$	$= x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F III
$\mathbf{B}_{13}$	$= x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	F IV
$\mathbf{B}_{14}$	$= -x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F IV
$\mathbf{B}_{15}$	$= -x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	F IV
$\mathbf{B}_{16}$	$= x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F IV
$\mathbf{B}_{17}$	$= x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	F V

$$\begin{aligned}
\mathbf{B}_{18} &= -x_5 \mathbf{a}_1 + \left(y_5 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_5 - \frac{1}{2}\right) \mathbf{a}_3 = -\left(ax_5 + c\left(z_5 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_5 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_5 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{F V} \\
\mathbf{B}_{19} &= -x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3 = -(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}} & (4e) & \text{F V} \\
\mathbf{B}_{20} &= x_5 \mathbf{a}_1 - \left(y_5 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_5 + \frac{1}{2}\right) \mathbf{a}_3 = \left(ax_5 + c\left(z_5 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_5 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_5 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{F V} \\
\mathbf{B}_{21} &= x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3 = (ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VI} \\
\mathbf{B}_{22} &= -x_6 \mathbf{a}_1 + \left(y_6 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_6 - \frac{1}{2}\right) \mathbf{a}_3 = -\left(ax_6 + c\left(z_6 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_6 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_6 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VI} \\
\mathbf{B}_{23} &= -x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3 = -(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VI} \\
\mathbf{B}_{24} &= x_6 \mathbf{a}_1 - \left(y_6 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_6 + \frac{1}{2}\right) \mathbf{a}_3 = \left(ax_6 + c\left(z_6 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_6 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_6 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VI} \\
\mathbf{B}_{25} &= x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3 = (ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VII} \\
\mathbf{B}_{26} &= -x_7 \mathbf{a}_1 + \left(y_7 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_7 - \frac{1}{2}\right) \mathbf{a}_3 = -\left(ax_7 + c\left(z_7 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_7 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_7 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VII} \\
\mathbf{B}_{27} &= -x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3 = -(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VII} \\
\mathbf{B}_{28} &= x_7 \mathbf{a}_1 - \left(y_7 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_7 + \frac{1}{2}\right) \mathbf{a}_3 = \left(ax_7 + c\left(z_7 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_7 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_7 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VII} \\
\mathbf{B}_{29} &= x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3 = (ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}} & (4e) & \text{K I} \\
\mathbf{B}_{30} &= -x_8 \mathbf{a}_1 + \left(y_8 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_8 - \frac{1}{2}\right) \mathbf{a}_3 = -\left(ax_8 + c\left(z_8 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_8 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_8 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{K I} \\
\mathbf{B}_{31} &= -x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3 = -(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}} & (4e) & \text{K I} \\
\mathbf{B}_{32} &= x_8 \mathbf{a}_1 - \left(y_8 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_8 + \frac{1}{2}\right) \mathbf{a}_3 = \left(ax_8 + c\left(z_8 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_8 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_8 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{K I} \\
\mathbf{B}_{33} &= x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 + z_9 \mathbf{a}_3 = (ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}} & (4e) & \text{K II} \\
\mathbf{B}_{34} &= -x_9 \mathbf{a}_1 + \left(y_9 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_9 - \frac{1}{2}\right) \mathbf{a}_3 = -\left(ax_9 + c\left(z_9 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_9 + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_9 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{K II} \\
\mathbf{B}_{35} &= -x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 - z_9 \mathbf{a}_3 = -(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} - cz_9 \sin \beta \hat{\mathbf{z}} & (4e) & \text{K II} \\
\mathbf{B}_{36} &= x_9 \mathbf{a}_1 - \left(y_9 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_9 + \frac{1}{2}\right) \mathbf{a}_3 = \left(ax_9 + c\left(z_9 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_9 - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_9 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{K II} \\
\mathbf{B}_{37} &= x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3 = (ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} + cz_{10} \sin \beta \hat{\mathbf{z}} & (4e) & \text{Nb I} \\
\mathbf{B}_{38} &= -x_{10} \mathbf{a}_1 + \left(y_{10} + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_{10} - \frac{1}{2}\right) \mathbf{a}_3 = -\left(ax_{10} + c\left(z_{10} - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + b\left(y_{10} + \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_{10} - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{Nb I} \\
\mathbf{B}_{39} &= -x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3 = -(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} - cz_{10} \sin \beta \hat{\mathbf{z}} & (4e) & \text{Nb I} \\
\mathbf{B}_{40} &= x_{10} \mathbf{a}_1 - \left(y_{10} - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_{10} + \frac{1}{2}\right) \mathbf{a}_3 = \left(ax_{10} + c\left(z_{10} + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - b\left(y_{10} - \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_{10} + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} & (4e) & \text{Nb I}
\end{aligned}$$

References

- [1] G. M. Brown and L. A. Walker, *Refinement of the structure of potassium heptafluoronioate, $K_2\text{NbF}_7$, from neutron-diffraction data*, Acta Cryst. **20**, 220–229 (1966), doi:10.1107/S0365110X66000458.

Found in

- [1] C. C. Torardi, L. H. Brixner, and G. Blasse, *Structure and luminescence of $K_2\text{TaF}_7$ and $K_2\text{NbF}_7$* , J. Solid State Chem. **67**, 21–25 (1987), doi:10.1016/0022-4596(87)90333-1.

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D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.