

Te[OH]₆ Structure (*Obsolete*): A6B_cF224_228_h_c-001

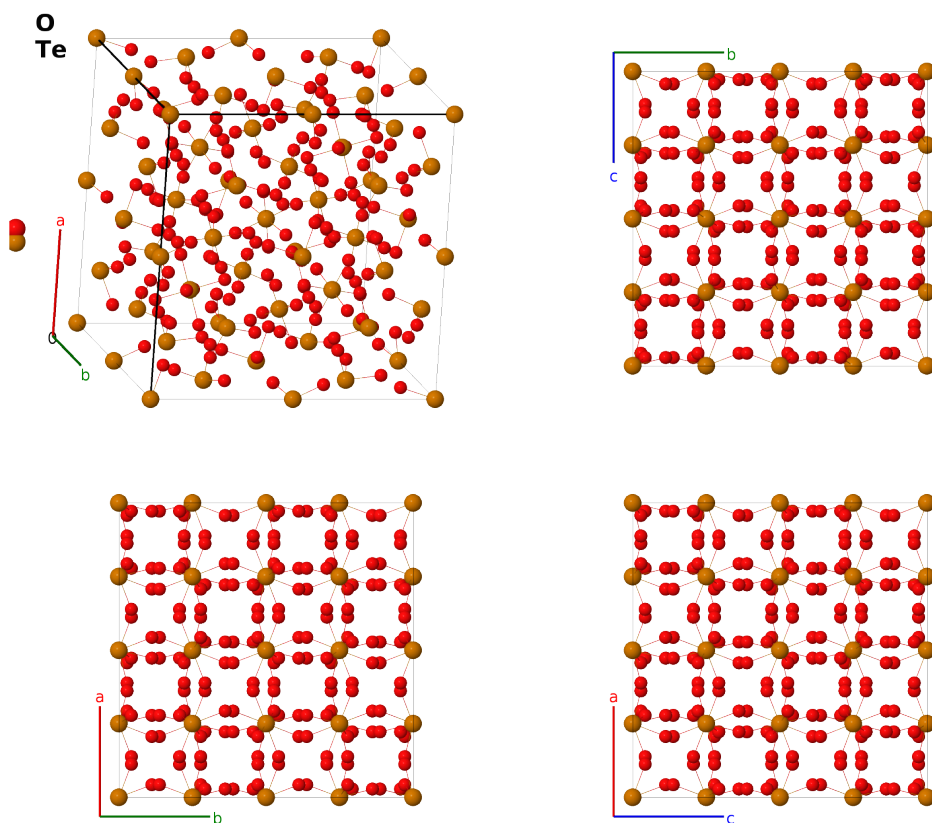
This structure previously used the label(s) **A6B_cF224_228_h_c**. Calls to these addresses will be redirected here.

Cite this page as:

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- D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

<https://aflow.org/prototype-encyclopedia/MSL9>

https://aflow.org/prototype-encyclopedia/A6B_cF224_228_h_c-001



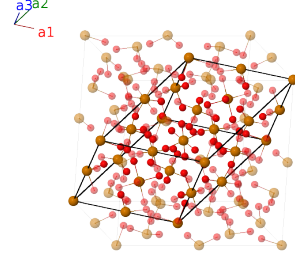
Prototype	H ₆ O ₆ Te
AFLOW prototype label	A6B_cF224_228_h_c-001
ICSD	2390
CCDC	1592291
Pearson symbol	cF224
Space group number	228
Space group symbol	$Fd\bar{3}c$

AFLOW prototype command `aflow --proto=A6B_cF224_228_h_c-001`
 `--params=a, x2, y2, z2`

- (Kirckpatrick, 1926) did not find the locations of the hydrogen atoms. When these were located by (Mullica, 1980) it was found that the true structure is in space group $F4_132$ #210.
- There is no ICSD entry for (Kirckpatrick, 1926). The ICSD/CCDC entries provided are from (Falak, 1978).

Face-centered Cubic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$=$	0	$=$	0	(32c) Te I
$\mathbf{B}_2$	$=$	$\frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + \frac{1}{4}a \hat{\mathbf{y}}$	(32c) Te I
$\mathbf{B}_3$	$=$	$\frac{1}{2} \mathbf{a}_2$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + \frac{1}{4}a \hat{\mathbf{z}}$	(32c) Te I
$\mathbf{B}_4$	$=$	$\frac{1}{2} \mathbf{a}_1$	$=$	$\frac{1}{4}a \hat{\mathbf{y}} + \frac{1}{4}a \hat{\mathbf{z}}$	(32c) Te I
$\mathbf{B}_5$	$=$	$\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + \frac{1}{4}a \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}}$	(32c) Te I
$\mathbf{B}_6$	$=$	$\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}}$	(32c) Te I
$\mathbf{B}_7$	$=$	$\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{4}a \hat{\mathbf{z}}$	(32c) Te I
$\mathbf{B}_8$	$=$	$\frac{1}{2} \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{4}a \hat{\mathbf{y}} + \frac{1}{4}a \hat{\mathbf{z}}$	(32c) Te I
$\mathbf{B}_9$	$=$	$(-x_2 + y_2 + z_2) \mathbf{a}_1 +$ $(x_2 - y_2 + z_2) \mathbf{a}_2 +$ $(x_2 + y_2 - z_2) \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} + ay_2 \hat{\mathbf{y}} + az_2 \hat{\mathbf{z}}$	(192h) O I
$\mathbf{B}_{10}$	$=$	$(x_2 - y_2 + z_2) \mathbf{a}_1 +$ $(-x_2 + y_2 + z_2) \mathbf{a}_2 -$ $(x_2 + y_2 + z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(x_2 - \frac{1}{4}) \hat{\mathbf{x}} - a(y_2 - \frac{1}{4}) \hat{\mathbf{y}} + az_2 \hat{\mathbf{z}}$	(192h) O I
$\mathbf{B}_{11}$	$=$	$(x_2 + y_2 - z_2) \mathbf{a}_1 -$ $(x_2 + y_2 + z_2 - \frac{1}{2}) \mathbf{a}_2 +$ $(-x_2 + y_2 + z_2) \mathbf{a}_3$	$=$	$-a(x_2 - \frac{1}{4}) \hat{\mathbf{x}} + ay_2 \hat{\mathbf{y}} - a(z_2 - \frac{1}{4}) \hat{\mathbf{z}}$	(192h) O I
$\mathbf{B}_{12}$	$=$	$-(x_2 + y_2 + z_2 - \frac{1}{2}) \mathbf{a}_1 +$ $(x_2 + y_2 - z_2) \mathbf{a}_2 +$ $(x_2 - y_2 + z_2) \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} - a(y_2 - \frac{1}{4}) \hat{\mathbf{y}} - a(z_2 - \frac{1}{4}) \hat{\mathbf{z}}$	(192h) O I
$\mathbf{B}_{13}$	$=$	$(x_2 + y_2 - z_2) \mathbf{a}_1 +$ $(-x_2 + y_2 + z_2) \mathbf{a}_2 +$ $(x_2 - y_2 + z_2) \mathbf{a}_3$	$=$	$az_2 \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} + ay_2 \hat{\mathbf{z}}$	(192h) O I

$\mathbf{B}_{14}$	$=$	$- \left(x_2 + y_2 + z_2 - \frac{1}{2}\right) \mathbf{a}_1 +$ $(x_2 - y_2 + z_2) \mathbf{a}_2 +$ $(-x_2 + y_2 + z_2) \mathbf{a}_3$	$=$	$az_2 \hat{\mathbf{x}} - a \left(x_2 - \frac{1}{4}\right) \hat{\mathbf{y}} - a \left(y_2 - \frac{1}{4}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{15}$	$=$	$(-x_2 + y_2 + z_2) \mathbf{a}_1 +$ $(x_2 + y_2 - z_2) \mathbf{a}_2 -$ $(x_2 + y_2 + z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a \left(z_2 - \frac{1}{4}\right) \hat{\mathbf{x}} - a \left(x_2 - \frac{1}{4}\right) \hat{\mathbf{y}} + ay_2 \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{16}$	$=$	$(x_2 - y_2 + z_2) \mathbf{a}_1 -$ $(x_2 + y_2 + z_2 - \frac{1}{2}) \mathbf{a}_2 +$ $(x_2 + y_2 - z_2) \mathbf{a}_3$	$=$	$-a \left(z_2 - \frac{1}{4}\right) \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} - a \left(y_2 - \frac{1}{4}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{17}$	$=$	$(x_2 - y_2 + z_2) \mathbf{a}_1 +$ $(x_2 + y_2 - z_2) \mathbf{a}_2 +$ $(-x_2 + y_2 + z_2) \mathbf{a}_3$	$=$	$ay_2 \hat{\mathbf{x}} + az_2 \hat{\mathbf{y}} + ax_2 \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{18}$	$=$	$(-x_2 + y_2 + z_2) \mathbf{a}_1 -$ $(x_2 + y_2 + z_2 - \frac{1}{2}) \mathbf{a}_2 +$ $(x_2 - y_2 + z_2) \mathbf{a}_3$	$=$	$-a \left(y_2 - \frac{1}{4}\right) \hat{\mathbf{x}} + az_2 \hat{\mathbf{y}} - a \left(x_2 - \frac{1}{4}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{19}$	$=$	$- \left(x_2 + y_2 + z_2 - \frac{1}{2}\right) \mathbf{a}_1 +$ $(-x_2 + y_2 + z_2) \mathbf{a}_2 +$ $(x_2 + y_2 - z_2) \mathbf{a}_3$	$=$	$ay_2 \hat{\mathbf{x}} - a \left(z_2 - \frac{1}{4}\right) \hat{\mathbf{y}} - a \left(x_2 - \frac{1}{4}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{20}$	$=$	$(x_2 + y_2 - z_2) \mathbf{a}_1 +$ $(x_2 - y_2 + z_2) \mathbf{a}_2 -$ $(x_2 + y_2 + z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a \left(y_2 - \frac{1}{4}\right) \hat{\mathbf{x}} - a \left(z_2 - \frac{1}{4}\right) \hat{\mathbf{y}} + ax_2 \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{21}$	$=$	$(x_2 - y_2 - z_2 + \frac{1}{2}) \mathbf{a}_1 -$ $(x_2 - y_2 + z_2 - \frac{1}{2}) \mathbf{a}_2 +$ $(x_2 + y_2 + z_2) \mathbf{a}_3$	$=$	$a \left(y_2 + \frac{1}{4}\right) \hat{\mathbf{x}} + a \left(x_2 + \frac{1}{4}\right) \hat{\mathbf{y}} - a \left(z_2 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{22}$	$=$	$- \left(x_2 - y_2 + z_2 - \frac{1}{2}\right) \mathbf{a}_1 +$ $(x_2 - y_2 - z_2 + \frac{1}{2}) \mathbf{a}_2 -$ $(x_2 + y_2 - z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a \left(y_2 - \frac{1}{2}\right) \hat{\mathbf{x}} - a \left(x_2 - \frac{1}{2}\right) \hat{\mathbf{y}} - a \left(z_2 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{23}$	$=$	$- \left(x_2 + y_2 - z_2 - \frac{1}{2}\right) \mathbf{a}_1 +$ $(x_2 + y_2 + z_2) \mathbf{a}_2 -$ $(x_2 - y_2 + z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$a \left(y_2 + \frac{1}{4}\right) \hat{\mathbf{x}} - a \left(x_2 - \frac{1}{2}\right) \hat{\mathbf{y}} + a \left(z_2 + \frac{1}{4}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{24}$	$=$	$(x_2 + y_2 + z_2) \mathbf{a}_1 -$ $(x_2 + y_2 - z_2 - \frac{1}{2}) \mathbf{a}_2 +$ $(x_2 - y_2 - z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a \left(y_2 - \frac{1}{2}\right) \hat{\mathbf{x}} + a \left(x_2 + \frac{1}{4}\right) \hat{\mathbf{y}} + a \left(z_2 + \frac{1}{4}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{25}$	$=$	$- \left(x_2 + y_2 - z_2 - \frac{1}{2}\right) \mathbf{a}_1 +$ $(x_2 - y_2 - z_2 + \frac{1}{2}) \mathbf{a}_2 +$ $(x_2 + y_2 + z_2) \mathbf{a}_3$	$=$	$a \left(x_2 + \frac{1}{4}\right) \hat{\mathbf{x}} + a \left(z_2 + \frac{1}{4}\right) \hat{\mathbf{y}} - a \left(y_2 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{26}$	$=$	$(x_2 + y_2 + z_2) \mathbf{a}_1 -$ $(x_2 - y_2 + z_2 - \frac{1}{2}) \mathbf{a}_2 -$ $(x_2 + y_2 - z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a \left(x_2 - \frac{1}{2}\right) \hat{\mathbf{x}} + a \left(z_2 + \frac{1}{4}\right) \hat{\mathbf{y}} + a \left(y_2 + \frac{1}{4}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{27}$	$=$	$(x_2 - y_2 - z_2 + \frac{1}{2}) \mathbf{a}_1 -$ $(x_2 + y_2 - z_2 - \frac{1}{2}) \mathbf{a}_2 -$ $(x_2 - y_2 + z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a \left(x_2 - \frac{1}{2}\right) \hat{\mathbf{x}} - a \left(z_2 - \frac{1}{2}\right) \hat{\mathbf{y}} - a \left(y_2 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{28}$	$=$	$- \left(x_2 - y_2 + z_2 - \frac{1}{2}\right) \mathbf{a}_1 +$ $(x_2 + y_2 + z_2) \mathbf{a}_2 +$ $(x_2 - y_2 - z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$a \left(x_2 + \frac{1}{4}\right) \hat{\mathbf{x}} - a \left(z_2 - \frac{1}{2}\right) \hat{\mathbf{y}} + a \left(y_2 + \frac{1}{4}\right) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{29}$	$=$	$- \left(x_2 - y_2 + z_2 - \frac{1}{2}\right) \mathbf{a}_1 -$ $(x_2 + y_2 - z_2 - \frac{1}{2}) \mathbf{a}_2 +$ $(x_2 + y_2 + z_2) \mathbf{a}_3$	$=$	$a \left(z_2 + \frac{1}{4}\right) \hat{\mathbf{x}} + a \left(y_2 + \frac{1}{4}\right) \hat{\mathbf{y}} - a \left(x_2 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(192h)	O I

$\mathbf{B}_{30} =$	$(x_2 - y_2 - z_2 + \frac{1}{2}) \mathbf{a}_1 +$ $(x_2 + y_2 + z_2) \mathbf{a}_2 -$ $(x_2 + y_2 - z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$a(z_2 + \frac{1}{4}) \hat{\mathbf{x}} - a(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + a(x_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{31} =$	$(x_2 + y_2 + z_2) \mathbf{a}_1 +$ $(x_2 - y_2 - z_2 + \frac{1}{2}) \mathbf{a}_2 -$ $(x_2 - y_2 + z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(z_2 - \frac{1}{2}) \hat{\mathbf{x}} + a(y_2 + \frac{1}{4}) \hat{\mathbf{y}} + a(x_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{32} =$	$-(x_2 + y_2 - z_2 - \frac{1}{2}) \mathbf{a}_1 -$ $(x_2 - y_2 + z_2 - \frac{1}{2}) \mathbf{a}_2 +$ $(x_2 - y_2 - z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a(z_2 - \frac{1}{2}) \hat{\mathbf{x}} - a(y_2 - \frac{1}{2}) \hat{\mathbf{y}} - a(x_2 - \frac{1}{2}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{33} =$	$(x_2 - y_2 - z_2) \mathbf{a}_1 -$ $(x_2 - y_2 + z_2) \mathbf{a}_2 -$ $(x_2 + y_2 - z_2) \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} - ay_2 \hat{\mathbf{y}} - az_2 \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{34} =$	$-(x_2 - y_2 + z_2) \mathbf{a}_1 +$ $(x_2 - y_2 - z_2) \mathbf{a}_2 +$ $(x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$a(x_2 + \frac{1}{4}) \hat{\mathbf{x}} + a(y_2 + \frac{1}{4}) \hat{\mathbf{y}} - az_2 \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{35} =$	$-(x_2 + y_2 - z_2) \mathbf{a}_1 +$ $(x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_2 +$ $(x_2 - y_2 - z_2) \mathbf{a}_3$	$=$	$a(x_2 + \frac{1}{4}) \hat{\mathbf{x}} - ay_2 \hat{\mathbf{y}} + a(z_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{36} =$	$(x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_1 -$ $(x_2 + y_2 - z_2) \mathbf{a}_2 -$ $(x_2 - y_2 + z_2) \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} + a(y_2 + \frac{1}{4}) \hat{\mathbf{y}} + a(z_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{37} =$	$-(x_2 + y_2 - z_2) \mathbf{a}_1 +$ $(x_2 - y_2 - z_2) \mathbf{a}_2 -$ $(x_2 - y_2 + z_2) \mathbf{a}_3$	$=$	$-az_2 \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} - ay_2 \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{38} =$	$(x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_1 -$ $(x_2 - y_2 + z_2) \mathbf{a}_2 +$ $(x_2 - y_2 - z_2) \mathbf{a}_3$	$=$	$-az_2 \hat{\mathbf{x}} + a(x_2 + \frac{1}{4}) \hat{\mathbf{y}} + a(y_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{39} =$	$(x_2 - y_2 - z_2) \mathbf{a}_1 -$ $(x_2 + y_2 - z_2) \mathbf{a}_2 +$ $(x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$a(z_2 + \frac{1}{4}) \hat{\mathbf{x}} + a(x_2 + \frac{1}{4}) \hat{\mathbf{y}} - ay_2 \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{40} =$	$-(x_2 - y_2 + z_2) \mathbf{a}_1 +$ $(x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_2 -$ $(x_2 + y_2 - z_2) \mathbf{a}_3$	$=$	$a(z_2 + \frac{1}{4}) \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} + a(y_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{41} =$	$-(x_2 - y_2 + z_2) \mathbf{a}_1 -$ $(x_2 + y_2 - z_2) \mathbf{a}_2 +$ $(x_2 - y_2 - z_2) \mathbf{a}_3$	$=$	$-ay_2 \hat{\mathbf{x}} - az_2 \hat{\mathbf{y}} - ax_2 \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{42} =$	$(x_2 - y_2 - z_2) \mathbf{a}_1 +$ $(x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_2 -$ $(x_2 - y_2 + z_2) \mathbf{a}_3$	$=$	$a(y_2 + \frac{1}{4}) \hat{\mathbf{x}} - az_2 \hat{\mathbf{y}} + a(x_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{43} =$	$(x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_1 +$ $(x_2 - y_2 - z_2) \mathbf{a}_2 -$ $(x_2 + y_2 - z_2) \mathbf{a}_3$	$=$	$-ay_2 \hat{\mathbf{x}} + a(z_2 + \frac{1}{4}) \hat{\mathbf{y}} + a(x_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{44} =$	$-(x_2 + y_2 - z_2) \mathbf{a}_1 -$ $(x_2 - y_2 + z_2) \mathbf{a}_2 +$ $(x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$a(y_2 + \frac{1}{4}) \hat{\mathbf{x}} + a(z_2 + \frac{1}{4}) \hat{\mathbf{y}} - ax_2 \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{45} =$	$(-x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_1 +$ $(x_2 - y_2 + z_2 + \frac{1}{2}) \mathbf{a}_2 -$ $(x_2 + y_2 + z_2) \mathbf{a}_3$	$=$	$-a(y_2 - \frac{1}{4}) \hat{\mathbf{x}} - a(x_2 - \frac{1}{4}) \hat{\mathbf{y}} + a(z_2 + \frac{1}{2}) \hat{\mathbf{z}}$	(192h)	O I
$\mathbf{B}_{46} =$	$(x_2 - y_2 + z_2 + \frac{1}{2}) \mathbf{a}_1 +$ $(-x_2 + y_2 + z_2 + \frac{1}{2}) \mathbf{a}_2 +$ $(x_2 + y_2 - z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$a(y_2 + \frac{1}{2}) \hat{\mathbf{x}} + a(x_2 + \frac{1}{2}) \hat{\mathbf{y}} + a(z_2 + \frac{1}{2}) \hat{\mathbf{z}}$	(192h)	O I

$$\begin{aligned}
\mathbf{B}_{47} &= \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \\ x_2 - y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_2 + y_2 + z_2 \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_2 + y_2 + z_2 \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_3 &= -a \left(y_2 - \frac{1}{4} \right) \hat{\mathbf{x}} + a \left(x_2 + \frac{1}{2} \right) \hat{\mathbf{y}} - a \left(z_2 - \frac{1}{4} \right) \hat{\mathbf{z}} & (192h) & \text{O I} \\
\mathbf{B}_{48} &= \begin{pmatrix} - (x_2 + y_2 + z_2) \\ x_2 + y_2 - z_2 + \frac{1}{2} \\ -x_2 + y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_3 &= a \left(y_2 + \frac{1}{2} \right) \hat{\mathbf{x}} - a \left(x_2 - \frac{1}{4} \right) \hat{\mathbf{y}} - a \left(z_2 - \frac{1}{4} \right) \hat{\mathbf{z}} & (192h) & \text{O I} \\
\mathbf{B}_{49} &= \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \end{pmatrix} \mathbf{a}_3 &= -a \left(x_2 - \frac{1}{4} \right) \hat{\mathbf{x}} - a \left(z_2 - \frac{1}{4} \right) \hat{\mathbf{y}} + a \left(y_2 + \frac{1}{2} \right) \hat{\mathbf{z}} & (192h) & \text{O I} \\
\mathbf{B}_{50} &= \begin{pmatrix} - (x_2 + y_2 + z_2) \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_3 &= a \left(x_2 + \frac{1}{2} \right) \hat{\mathbf{x}} - a \left(z_2 - \frac{1}{4} \right) \hat{\mathbf{y}} - a \left(y_2 - \frac{1}{4} \right) \hat{\mathbf{z}} & (192h) & \text{O I} \\
\mathbf{B}_{51} &= \begin{pmatrix} -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_3 &= a \left(x_2 + \frac{1}{2} \right) \hat{\mathbf{x}} + a \left(z_2 + \frac{1}{2} \right) \hat{\mathbf{y}} + a \left(y_2 + \frac{1}{2} \right) \hat{\mathbf{z}} & (192h) & \text{O I} \\
\mathbf{B}_{52} &= \begin{pmatrix} x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \\ -x_2 + y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_2 + y_2 + z_2 \\ -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_2 + y_2 + z_2 \\ -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \end{pmatrix} \mathbf{a}_3 &= -a \left(x_2 - \frac{1}{4} \right) \hat{\mathbf{x}} + a \left(z_2 + \frac{1}{2} \right) \hat{\mathbf{y}} - a \left(y_2 - \frac{1}{4} \right) \hat{\mathbf{z}} & (192h) & \text{O I} \\
\mathbf{B}_{53} &= \begin{pmatrix} x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \\ x_2 + y_2 + z_2 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \\ x_2 + y_2 + z_2 \end{pmatrix} \mathbf{a}_3 &= -a \left(z_2 - \frac{1}{4} \right) \hat{\mathbf{x}} - a \left(y_2 - \frac{1}{4} \right) \hat{\mathbf{y}} + a \left(x_2 + \frac{1}{2} \right) \hat{\mathbf{z}} & (192h) & \text{O I} \\
\mathbf{B}_{54} &= \begin{pmatrix} -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 + y_2 + z_2 \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_2 + y_2 + z_2 \\ x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_2 + y_2 + z_2 \\ x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 + y_2 - z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_3 &= -a \left(z_2 - \frac{1}{4} \right) \hat{\mathbf{x}} + a \left(y_2 + \frac{1}{2} \right) \hat{\mathbf{y}} - a \left(x_2 - \frac{1}{4} \right) \hat{\mathbf{z}} & (192h) & \text{O I} \\
\mathbf{B}_{55} &= \begin{pmatrix} - (x_2 + y_2 + z_2) \\ -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} -x_2 + y_2 + z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_3 &= a \left(z_2 + \frac{1}{2} \right) \hat{\mathbf{x}} - a \left(y_2 - \frac{1}{4} \right) \hat{\mathbf{y}} - a \left(x_2 - \frac{1}{4} \right) \hat{\mathbf{z}} & (192h) & \text{O I} \\
\mathbf{B}_{56} &= \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ -x_2 + y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ -x_2 + y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_2 + y_2 - z_2 + \frac{1}{2} \\ x_2 - y_2 + z_2 + \frac{1}{2} \\ -x_2 + y_2 + z_2 + \frac{1}{2} \end{pmatrix} \mathbf{a}_3 &= a \left(z_2 + \frac{1}{2} \right) \hat{\mathbf{x}} + a \left(y_2 + \frac{1}{2} \right) \hat{\mathbf{y}} + a \left(x_2 + \frac{1}{2} \right) \hat{\mathbf{z}} & (192h) & \text{O I}
\end{aligned}$$

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