

# In<sub>4</sub>Se<sub>3</sub> Structure:

## A4B3\_oP28\_58\_4g\_3g-001

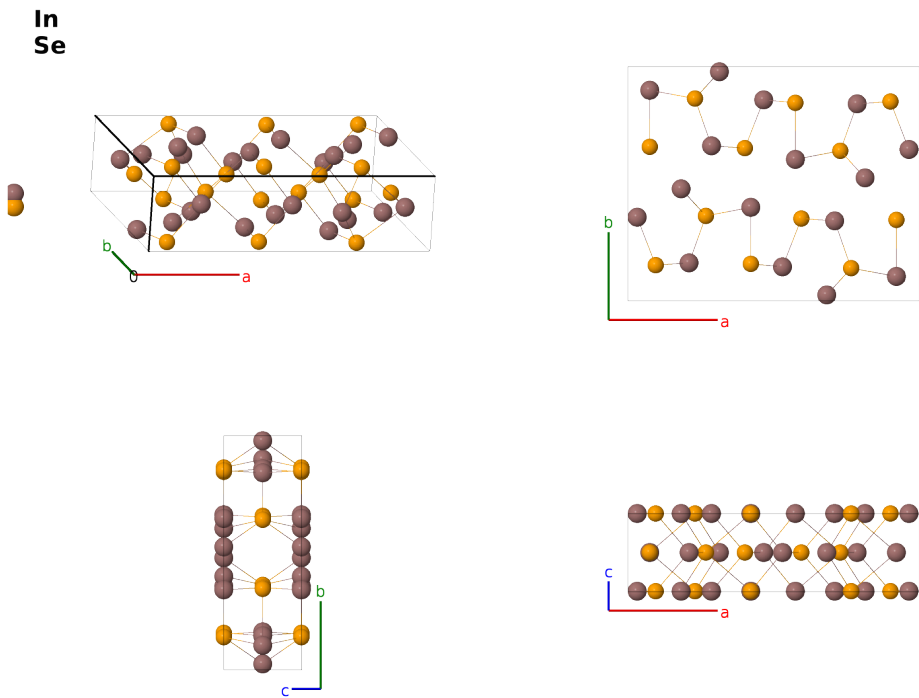
This structure previously used the label(s) **A4B3\_oP28\_58\_4g\_3g**. Calls to these addresses will be redirected here.

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<https://aflow.org/prototype-encyclopedia/B01P>

[https://aflow.org/prototype-encyclopedia/A4B3\\_oP28\\_58\\_4g\\_3g-001](https://aflow.org/prototype-encyclopedia/A4B3_oP28_58_4g_3g-001)



|                         |                                                                                                                                                                                                                                                                                                          |
|-------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Prototype               | In <sub>4</sub> Se <sub>3</sub>                                                                                                                                                                                                                                                                          |
| AFLOW prototype label   | A4B3_oP28_58_4g_3g-001                                                                                                                                                                                                                                                                                   |
| ICSD                    | 2601                                                                                                                                                                                                                                                                                                     |
| CCDC                    | 1592475                                                                                                                                                                                                                                                                                                  |
| Pearson symbol          | oP28                                                                                                                                                                                                                                                                                                     |
| Space group number      | 58                                                                                                                                                                                                                                                                                                       |
| Space group symbol      | <i>Pnnm</i>                                                                                                                                                                                                                                                                                              |
| AFLOW prototype command | <code>aflow --proto=A4B3_oP28_58_4g_3g-001</code><br><code>--params=a, b/a, c/a, x<sub>1</sub>, y<sub>1</sub>, x<sub>2</sub>, y<sub>2</sub>, x<sub>3</sub>, y<sub>3</sub>, x<sub>4</sub>, y<sub>4</sub>, x<sub>5</sub>, y<sub>5</sub>, x<sub>6</sub>, y<sub>6</sub>, x<sub>7</sub>, y<sub>7</sub></code> |

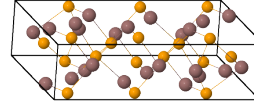
## Other compounds with this structure

In<sub>4</sub>Te<sub>3</sub>

## Simple Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \hat{\mathbf{z}}\end{aligned}$$

a2a3  
a1



## Basis vectors

|                   | Lattice<br>coordinates                                                                                                    |     | Cartesian<br>coordinates                                                                                                               | Wyckoff<br>position | Atom<br>type |
|-------------------|---------------------------------------------------------------------------------------------------------------------------|-----|----------------------------------------------------------------------------------------------------------------------------------------|---------------------|--------------|
| $\mathbf{B}_1$    | $= x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2$                                                                                   | $=$ | $ax_1 \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}}$                                                                                        | (4g)                | In I         |
| $\mathbf{B}_2$    | $= -x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2$                                                                                  | $=$ | $-ax_1 \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}}$                                                                                       | (4g)                | In I         |
| $\mathbf{B}_3$    | $= -\left(x_1 - \frac{1}{2}\right) \mathbf{a}_1 + \left(y_1 + \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | $=$ | $-a\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{x}} + b\left(y_1 + \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$ | (4g)                | In I         |
| $\mathbf{B}_4$    | $= \left(x_1 + \frac{1}{2}\right) \mathbf{a}_1 - \left(y_1 - \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$  | $=$ | $a\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{x}} - b\left(y_1 - \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$  | (4g)                | In I         |
| $\mathbf{B}_5$    | $= x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2$                                                                                   | $=$ | $ax_2 \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}}$                                                                                        | (4g)                | In II        |
| $\mathbf{B}_6$    | $= -x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2$                                                                                  | $=$ | $-ax_2 \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}}$                                                                                       | (4g)                | In II        |
| $\mathbf{B}_7$    | $= -\left(x_2 - \frac{1}{2}\right) \mathbf{a}_1 + \left(y_2 + \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | $=$ | $-a\left(x_2 - \frac{1}{2}\right) \hat{\mathbf{x}} + b\left(y_2 + \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$ | (4g)                | In II        |
| $\mathbf{B}_8$    | $= \left(x_2 + \frac{1}{2}\right) \mathbf{a}_1 - \left(y_2 - \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$  | $=$ | $a\left(x_2 + \frac{1}{2}\right) \hat{\mathbf{x}} - b\left(y_2 - \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$  | (4g)                | In II        |
| $\mathbf{B}_9$    | $= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2$                                                                                   | $=$ | $ax_3 \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}}$                                                                                        | (4g)                | In III       |
| $\mathbf{B}_{10}$ | $= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2$                                                                                  | $=$ | $-ax_3 \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}}$                                                                                       | (4g)                | In III       |
| $\mathbf{B}_{11}$ | $= -\left(x_3 - \frac{1}{2}\right) \mathbf{a}_1 + \left(y_3 + \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | $=$ | $-a\left(x_3 - \frac{1}{2}\right) \hat{\mathbf{x}} + b\left(y_3 + \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$ | (4g)                | In III       |
| $\mathbf{B}_{12}$ | $= \left(x_3 + \frac{1}{2}\right) \mathbf{a}_1 - \left(y_3 - \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$  | $=$ | $a\left(x_3 + \frac{1}{2}\right) \hat{\mathbf{x}} - b\left(y_3 - \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$  | (4g)                | In III       |
| $\mathbf{B}_{13}$ | $= x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2$                                                                                   | $=$ | $ax_4 \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}}$                                                                                        | (4g)                | In IV        |
| $\mathbf{B}_{14}$ | $= -x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2$                                                                                  | $=$ | $-ax_4 \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}}$                                                                                       | (4g)                | In IV        |
| $\mathbf{B}_{15}$ | $= -\left(x_4 - \frac{1}{2}\right) \mathbf{a}_1 + \left(y_4 + \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | $=$ | $-a\left(x_4 - \frac{1}{2}\right) \hat{\mathbf{x}} + b\left(y_4 + \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$ | (4g)                | In IV        |
| $\mathbf{B}_{16}$ | $= \left(x_4 + \frac{1}{2}\right) \mathbf{a}_1 - \left(y_4 - \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$  | $=$ | $a\left(x_4 + \frac{1}{2}\right) \hat{\mathbf{x}} - b\left(y_4 - \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$  | (4g)                | In IV        |
| $\mathbf{B}_{17}$ | $= x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2$                                                                                   | $=$ | $ax_5 \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}}$                                                                                        | (4g)                | Se I         |
| $\mathbf{B}_{18}$ | $= -x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2$                                                                                  | $=$ | $-ax_5 \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}}$                                                                                       | (4g)                | Se I         |
| $\mathbf{B}_{19}$ | $= -\left(x_5 - \frac{1}{2}\right) \mathbf{a}_1 + \left(y_5 + \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | $=$ | $-a\left(x_5 - \frac{1}{2}\right) \hat{\mathbf{x}} + b\left(y_5 + \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$ | (4g)                | Se I         |
| $\mathbf{B}_{20}$ | $= \left(x_5 + \frac{1}{2}\right) \mathbf{a}_1 - \left(y_5 - \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$  | $=$ | $a\left(x_5 + \frac{1}{2}\right) \hat{\mathbf{x}} - b\left(y_5 - \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$  | (4g)                | Se I         |
| $\mathbf{B}_{21}$ | $= x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2$                                                                                   | $=$ | $ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}}$                                                                                        | (4g)                | Se II        |
| $\mathbf{B}_{22}$ | $= -x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2$                                                                                  | $=$ | $-ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}}$                                                                                       | (4g)                | Se II        |

$$\begin{aligned}
\mathbf{B}_{23} &= -\left(x_6 - \frac{1}{2}\right) \mathbf{a}_1 + \left(y_6 + \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3 = -a\left(x_6 - \frac{1}{2}\right) \hat{\mathbf{x}} + b\left(y_6 + \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} & (4g) & \text{Se II} \\
\mathbf{B}_{24} &= \left(x_6 + \frac{1}{2}\right) \mathbf{a}_1 - \left(y_6 - \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3 = a\left(x_6 + \frac{1}{2}\right) \hat{\mathbf{x}} - b\left(y_6 - \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} & (4g) & \text{Se II} \\
\mathbf{B}_{25} &= x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 = ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} & (4g) & \text{Se III} \\
\mathbf{B}_{26} &= -x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 = -ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} & (4g) & \text{Se III} \\
\mathbf{B}_{27} &= -\left(x_7 - \frac{1}{2}\right) \mathbf{a}_1 + \left(y_7 + \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3 = -a\left(x_7 - \frac{1}{2}\right) \hat{\mathbf{x}} + b\left(y_7 + \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} & (4g) & \text{Se III} \\
\mathbf{B}_{28} &= \left(x_7 + \frac{1}{2}\right) \mathbf{a}_1 - \left(y_7 - \frac{1}{2}\right) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3 = a\left(x_7 + \frac{1}{2}\right) \hat{\mathbf{x}} - b\left(y_7 - \frac{1}{2}\right) \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} & (4g) & \text{Se III}
\end{aligned}$$

## References

- [1] J. H. C. Hogg, H. H. Sutherland, and D. J. Williams, *The crystal structure of tetraindium triselenide*, Acta Crystallogr. Sect. B **29**, 1590–1593 (1973), doi:10.1107/S0567740873005108.

## Found in

- [1] N. Benramdane and R. H. Misho, *Structural and optical properties of  $\text{In}_4\text{Se}_3$  thin films obtained by flash evaporation*, Sol. Energy Mater Sol. Cells **37**, 367–377 (1995), doi:10.1016/0927-0248(95)00031-3.

## First cited in

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