

Hg₃S₂I₂ Structure:

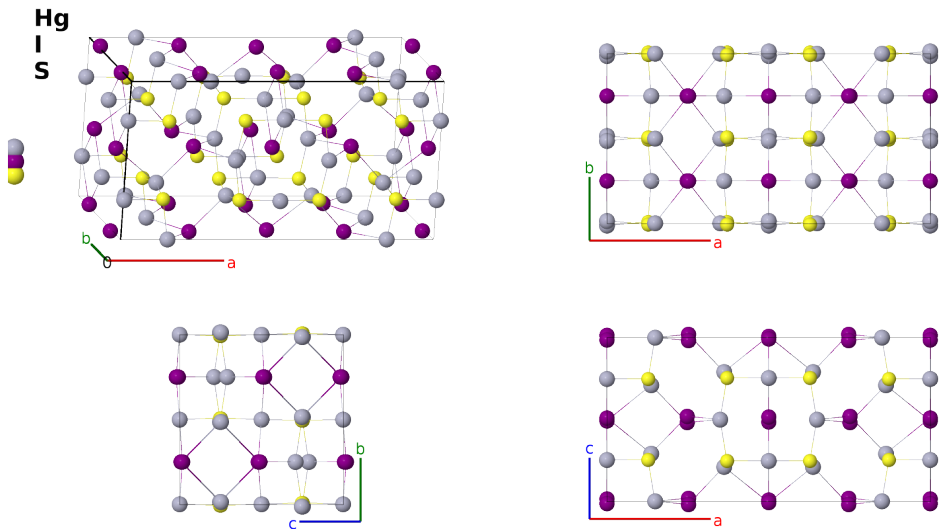
A3B2C2_oI56_74_fhi_2ei_j-001

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<https://aflow.org/prototype-encyclopedia/EXRV>

https://aflow.org/prototype-encyclopedia/A3B2C2_oI56_74_fhi_2ei_j-001



Prototype	Hg ₃ I ₂ S ₂
AFLOW prototype label	A3B2C2_oI56_74_fhi_2ei_j-001
ICSD	411154
CCDC	1726856
Pearson symbol	oI56
Space group number	74
Space group symbol	<i>Imma</i>
AFLOW prototype command	<pre>aflow --proto=A3B2C2_oI56_74_fhi_2ei_j-001 --params=a, b/a, c/a, z1, z2, x3, y4, z4, x5, z5, x6, z6, x7, y7, z7</pre>

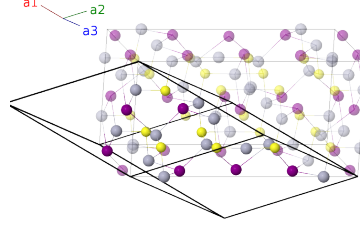
Other compounds with this structure

Hg₃Se₂I₂

- FINDSYN rotated this structure by 90° about the *z*-axis and shifted the origin by $(\mathbf{a}_1 + \mathbf{a}_2 + \mathbf{a}_3)/4$ compared to the structure in (Beck, 2000).

Body-centered Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= -\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} - \frac{1}{2}c \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= \left(z_1 + \frac{1}{4}\right) \mathbf{a}_1 + z_1 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}b \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(4e)	I I
$\mathbf{B}_2$	$= -\left(z_1 - \frac{3}{4}\right) \mathbf{a}_1 - z_1 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}b \hat{\mathbf{y}} - cz_1 \hat{\mathbf{z}}$	(4e)	I I
$\mathbf{B}_3$	$= \left(z_2 + \frac{1}{4}\right) \mathbf{a}_1 + z_2 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}b \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(4e)	I II
$\mathbf{B}_4$	$= -\left(z_2 - \frac{3}{4}\right) \mathbf{a}_1 - z_2 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}b \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$	(4e)	I II
$\mathbf{B}_5$	$= x_3 \mathbf{a}_2 + x_3 \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}}$	(8f)	Hg I
$\mathbf{B}_6$	$= \frac{1}{2} \mathbf{a}_1 - x_3 \mathbf{a}_2 - \left(x_3 - \frac{1}{2}\right) \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}}$	(8f)	Hg I
$\mathbf{B}_7$	$= -x_3 \mathbf{a}_2 - x_3 \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}}$	(8f)	Hg I
$\mathbf{B}_8$	$= \frac{1}{2} \mathbf{a}_1 + x_3 \mathbf{a}_2 + \left(x_3 + \frac{1}{2}\right) \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}}$	(8f)	Hg I
$\mathbf{B}_9$	$= (y_4 + z_4) \mathbf{a}_1 + z_4 \mathbf{a}_2 + y_4 \mathbf{a}_3$	$=$	$by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8h)	Hg II
$\mathbf{B}_{10}$	$= \left(-y_4 + z_4 + \frac{1}{2}\right) \mathbf{a}_1 + z_4 \mathbf{a}_2 - \left(y_4 - \frac{1}{2}\right) \mathbf{a}_3$	$=$	$-b \left(y_4 - \frac{1}{2}\right) \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8h)	Hg II
$\mathbf{B}_{11}$	$= \left(y_4 - z_4 + \frac{1}{2}\right) \mathbf{a}_1 - z_4 \mathbf{a}_2 + \left(y_4 + \frac{1}{2}\right) \mathbf{a}_3$	$=$	$b \left(y_4 + \frac{1}{2}\right) \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$	(8h)	Hg II
$\mathbf{B}_{12}$	$= -(y_4 + z_4) \mathbf{a}_1 - z_4 \mathbf{a}_2 - y_4 \mathbf{a}_3$	$=$	$-by_4 \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$	(8h)	Hg II
$\mathbf{B}_{13}$	$= \left(z_5 + \frac{1}{4}\right) \mathbf{a}_1 + (x_5 + z_5) \mathbf{a}_2 + \left(x_5 + \frac{1}{4}\right) \mathbf{a}_3$	$=$	$ax_5 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8i)	Hg III
$\mathbf{B}_{14}$	$= \left(z_5 + \frac{1}{4}\right) \mathbf{a}_1 - (x_5 - z_5) \mathbf{a}_2 - \left(x_5 - \frac{1}{4}\right) \mathbf{a}_3$	$=$	$-ax_5 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8i)	Hg III
$\mathbf{B}_{15}$	$= -\left(z_5 - \frac{3}{4}\right) \mathbf{a}_1 - (x_5 + z_5) \mathbf{a}_2 - \left(x_5 - \frac{3}{4}\right) \mathbf{a}_3$	$=$	$-ax_5 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$	(8i)	Hg III
$\mathbf{B}_{16}$	$= -\left(z_5 - \frac{3}{4}\right) \mathbf{a}_1 + (x_5 - z_5) \mathbf{a}_2 + \left(x_5 + \frac{3}{4}\right) \mathbf{a}_3$	$=$	$ax_5 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$	(8i)	Hg III
$\mathbf{B}_{17}$	$= \left(z_6 + \frac{1}{4}\right) \mathbf{a}_1 + (x_6 + z_6) \mathbf{a}_2 + \left(x_6 + \frac{1}{4}\right) \mathbf{a}_3$	$=$	$ax_6 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8i)	I III
$\mathbf{B}_{18}$	$= \left(z_6 + \frac{1}{4}\right) \mathbf{a}_1 - (x_6 - z_6) \mathbf{a}_2 - \left(x_6 - \frac{1}{4}\right) \mathbf{a}_3$	$=$	$-ax_6 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8i)	I III
$\mathbf{B}_{19}$	$= -\left(z_6 - \frac{3}{4}\right) \mathbf{a}_1 - (x_6 + z_6) \mathbf{a}_2 - \left(x_6 - \frac{3}{4}\right) \mathbf{a}_3$	$=$	$-ax_6 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}}$	(8i)	I III
$\mathbf{B}_{20}$	$= -\left(z_6 - \frac{3}{4}\right) \mathbf{a}_1 + (x_6 - z_6) \mathbf{a}_2 + \left(x_6 + \frac{3}{4}\right) \mathbf{a}_3$	$=$	$ax_6 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}}$	(8i)	I III
$\mathbf{B}_{21}$	$= (y_7 + z_7) \mathbf{a}_1 + (x_7 + z_7) \mathbf{a}_2 + (x_7 + y_7) \mathbf{a}_3$	$=$	$ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}}$	(16j)	S I

$$\begin{aligned}
\mathbf{B}_{22} &= \begin{pmatrix} -y_7 + z_7 + \frac{1}{2} \\ (x_7 - z_7) \mathbf{a}_2 - (x_7 + y_7 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} \mathbf{a}_1 - &= & -ax_7 \hat{\mathbf{x}} - b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16j) & \text{S I} \\
\mathbf{B}_{23} &= \begin{pmatrix} y_7 - z_7 + \frac{1}{2} \\ -x_7 + y_7 + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 - (x_7 + z_7) \mathbf{a}_2 + &= & -ax_7 \hat{\mathbf{x}} + b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16j) & \text{S I} \\
\mathbf{B}_{24} &= -(y_7 + z_7) \mathbf{a}_1 + (x_7 - z_7) \mathbf{a}_2 + &= & ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16j) & \text{S I} \\
&\quad (x_7 - y_7) \mathbf{a}_3 \\
\mathbf{B}_{25} &= -(y_7 + z_7) \mathbf{a}_1 - (x_7 + z_7) \mathbf{a}_2 - &= & -ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16j) & \text{S I} \\
&\quad (x_7 + y_7) \mathbf{a}_3 \\
\mathbf{B}_{26} &= \begin{pmatrix} y_7 - z_7 + \frac{1}{2} \\ (x_7 - z_7) \mathbf{a}_2 + (x_7 + y_7 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} \mathbf{a}_1 + &= & ax_7 \hat{\mathbf{x}} + b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16j) & \text{S I} \\
\mathbf{B}_{27} &= \begin{pmatrix} -y_7 + z_7 + \frac{1}{2} \\ (x_7 + z_7) \mathbf{a}_2 + (x_7 - y_7 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} \mathbf{a}_1 + &= & ax_7 \hat{\mathbf{x}} - b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16j) & \text{S I} \\
\mathbf{B}_{28} &= \begin{pmatrix} y_7 + z_7 \\ (x_7 - y_7) \mathbf{a}_3 \end{pmatrix} \mathbf{a}_1 - (x_7 - z_7) \mathbf{a}_2 - &= & -ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16j) & \text{S I}
\end{aligned}$$

References

- [1] J. Beck and S. Hedderich, *Synthesis and Crystal Structure of $\text{Hg}_3\text{S}_2\text{I}_2$ and $\text{Hg}_3\text{Se}_2\text{I}_2$, New Members of the $\text{Hg}_3\text{E}_2\text{X}_2$ Family*, Journal of Solid State Chemistry **151**, 73–76 (2000), doi:10.1006/jssc.1999.8624.

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