

PNCl₂ (*E*1₄) Structure: A2BC_tP32_86_2g_g-g-001

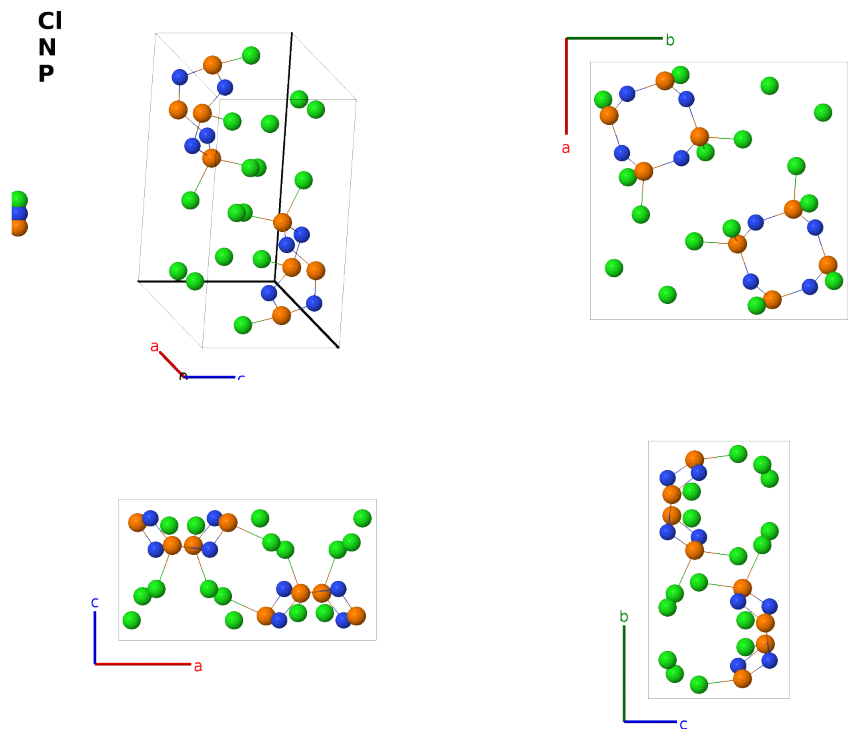
This structure previously used the label(s) **A2BC_tP32.86.2g_g-g**. Calls to these addresses will be redirected here.

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<https://aflow.org/prototype-encyclopedia/QLZ6>

https://aflow.org/prototype-encyclopedia/A2BC_tP32_86_2g_g-g-001

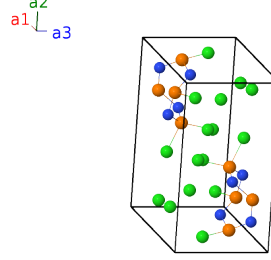


Prototype	Cl ₂ NP
AFLOW prototype label	A2BC_tP32_86_2g_g-g-001
<i>Strukturbericht</i> designation	<i>E</i> 1 ₄
ICSD	33711
CCDC	1606453
Pearson symbol	tP32
Space group number	86
Space group symbol	<i>P</i> 4 ₂ / <i>n</i>
AFLOW prototype command	<code>aflow --proto=A2BC_tP32_86_2g_g-g-001</code> <code>--params=<i>a</i>, <i>c/a</i>, <i>x</i>₁, <i>y</i>₁, <i>z</i>₁, <i>x</i>₂, <i>y</i>₂, <i>z</i>₂, <i>x</i>₃, <i>y</i>₃, <i>z</i>₃, <i>x</i>₄, <i>y</i>₄, <i>z</i>₄</code>

- (Ketellar, 1939) gave the atomic positions in setting 1 of space group $P4_2/n$ #86. We have shifted the origin to the inversion site for this lattice and present the atomic positions in setting 2.

Simple Tetragonal primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= a \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	$=$	$ax_1 \hat{\mathbf{x}} + ay_1 \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(8g)	Cl I
$\mathbf{B}_2$	$= -\left(x_1 - \frac{1}{2}\right) \mathbf{a}_1 - \left(y_1 - \frac{1}{2}\right) \mathbf{a}_2 + z_1 \mathbf{a}_3$	$=$	$-a\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{x}} - a\left(y_1 - \frac{1}{2}\right) \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(8g)	Cl I
$\mathbf{B}_3$	$= -y_1 \mathbf{a}_1 + \left(x_1 + \frac{1}{2}\right) \mathbf{a}_2 + \left(z_1 + \frac{1}{2}\right) \mathbf{a}_3$	$=$	$-ay_1 \hat{\mathbf{x}} + a\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_1 + \frac{1}{2}\right) \hat{\mathbf{z}}$	(8g)	Cl I
$\mathbf{B}_4$	$= \left(y_1 + \frac{1}{2}\right) \mathbf{a}_1 - x_1 \mathbf{a}_2 + \left(z_1 + \frac{1}{2}\right) \mathbf{a}_3$	$=$	$a\left(y_1 + \frac{1}{2}\right) \hat{\mathbf{x}} - ax_1 \hat{\mathbf{y}} + c\left(z_1 + \frac{1}{2}\right) \hat{\mathbf{z}}$	(8g)	Cl I
$\mathbf{B}_5$	$= -x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	$=$	$-ax_1 \hat{\mathbf{x}} - ay_1 \hat{\mathbf{y}} - cz_1 \hat{\mathbf{z}}$	(8g)	Cl I
$\mathbf{B}_6$	$= \left(x_1 + \frac{1}{2}\right) \mathbf{a}_1 + \left(y_1 + \frac{1}{2}\right) \mathbf{a}_2 - z_1 \mathbf{a}_3$	$=$	$a\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{x}} + a\left(y_1 + \frac{1}{2}\right) \hat{\mathbf{y}} - cz_1 \hat{\mathbf{z}}$	(8g)	Cl I
$\mathbf{B}_7$	$= y_1 \mathbf{a}_1 - \left(x_1 - \frac{1}{2}\right) \mathbf{a}_2 - \left(z_1 - \frac{1}{2}\right) \mathbf{a}_3$	$=$	$ay_1 \hat{\mathbf{x}} - a\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_1 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(8g)	Cl I
$\mathbf{B}_8$	$= -\left(y_1 - \frac{1}{2}\right) \mathbf{a}_1 + x_1 \mathbf{a}_2 - \left(z_1 - \frac{1}{2}\right) \mathbf{a}_3$	$=$	$-a\left(y_1 - \frac{1}{2}\right) \hat{\mathbf{x}} + ax_1 \hat{\mathbf{y}} - c\left(z_1 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(8g)	Cl I
$\mathbf{B}_9$	$= x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} + ay_2 \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8g)	Cl II
$\mathbf{B}_{10}$	$= -\left(x_2 - \frac{1}{2}\right) \mathbf{a}_1 - \left(y_2 - \frac{1}{2}\right) \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$-a\left(x_2 - \frac{1}{2}\right) \hat{\mathbf{x}} - a\left(y_2 - \frac{1}{2}\right) \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8g)	Cl II
$\mathbf{B}_{11}$	$= -y_2 \mathbf{a}_1 + \left(x_2 + \frac{1}{2}\right) \mathbf{a}_2 + \left(z_2 + \frac{1}{2}\right) \mathbf{a}_3$	$=$	$-ay_2 \hat{\mathbf{x}} + a\left(x_2 + \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_2 + \frac{1}{2}\right) \hat{\mathbf{z}}$	(8g)	Cl II
$\mathbf{B}_{12}$	$= \left(y_2 + \frac{1}{2}\right) \mathbf{a}_1 - x_2 \mathbf{a}_2 + \left(z_2 + \frac{1}{2}\right) \mathbf{a}_3$	$=$	$a\left(y_2 + \frac{1}{2}\right) \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} + c\left(z_2 + \frac{1}{2}\right) \hat{\mathbf{z}}$	(8g)	Cl II
$\mathbf{B}_{13}$	$= -x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} - ay_2 \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$	(8g)	Cl II
$\mathbf{B}_{14}$	$= \left(x_2 + \frac{1}{2}\right) \mathbf{a}_1 + \left(y_2 + \frac{1}{2}\right) \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$a\left(x_2 + \frac{1}{2}\right) \hat{\mathbf{x}} + a\left(y_2 + \frac{1}{2}\right) \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$	(8g)	Cl II
$\mathbf{B}_{15}$	$= y_2 \mathbf{a}_1 - \left(x_2 - \frac{1}{2}\right) \mathbf{a}_2 - \left(z_2 - \frac{1}{2}\right) \mathbf{a}_3$	$=$	$ay_2 \hat{\mathbf{x}} - a\left(x_2 - \frac{1}{2}\right) \hat{\mathbf{y}} - c\left(z_2 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(8g)	Cl II
$\mathbf{B}_{16}$	$= -\left(y_2 - \frac{1}{2}\right) \mathbf{a}_1 + x_2 \mathbf{a}_2 - \left(z_2 - \frac{1}{2}\right) \mathbf{a}_3$	$=$	$-a\left(y_2 - \frac{1}{2}\right) \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} - c\left(z_2 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(8g)	Cl II
$\mathbf{B}_{17}$	$= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} + ay_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8g)	N I
$\mathbf{B}_{18}$	$= -\left(x_3 - \frac{1}{2}\right) \mathbf{a}_1 - \left(y_3 - \frac{1}{2}\right) \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$-a\left(x_3 - \frac{1}{2}\right) \hat{\mathbf{x}} - a\left(y_3 - \frac{1}{2}\right) \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8g)	N I
$\mathbf{B}_{19}$	$= -y_3 \mathbf{a}_1 + \left(x_3 + \frac{1}{2}\right) \mathbf{a}_2 + \left(z_3 + \frac{1}{2}\right) \mathbf{a}_3$	$=$	$-ay_3 \hat{\mathbf{x}} + a\left(x_3 + \frac{1}{2}\right) \hat{\mathbf{y}} + c\left(z_3 + \frac{1}{2}\right) \hat{\mathbf{z}}$	(8g)	N I

$$\begin{aligned}
\mathbf{B}_{20} &= (y_3 + \tfrac{1}{2}) \mathbf{a}_1 - x_3 \mathbf{a}_2 + (z_3 + \tfrac{1}{2}) \mathbf{a}_3 = a(y_3 + \tfrac{1}{2}) \hat{\mathbf{x}} - ax_3 \hat{\mathbf{y}} + c(z_3 + \tfrac{1}{2}) \hat{\mathbf{z}} & (8g) & \text{N I} \\
\mathbf{B}_{21} &= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3 = -ax_3 \hat{\mathbf{x}} - ay_3 \hat{\mathbf{y}} - cz_3 \hat{\mathbf{z}} & (8g) & \text{N I} \\
\mathbf{B}_{22} &= (x_3 + \tfrac{1}{2}) \mathbf{a}_1 + (y_3 + \tfrac{1}{2}) \mathbf{a}_2 - z_3 \mathbf{a}_3 = a(x_3 + \tfrac{1}{2}) \hat{\mathbf{x}} + a(y_3 + \tfrac{1}{2}) \hat{\mathbf{y}} - cz_3 \hat{\mathbf{z}} & (8g) & \text{N I} \\
\mathbf{B}_{23} &= y_3 \mathbf{a}_1 - (x_3 - \tfrac{1}{2}) \mathbf{a}_2 - (z_3 - \tfrac{1}{2}) \mathbf{a}_3 = ay_3 \hat{\mathbf{x}} - a(x_3 - \tfrac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \tfrac{1}{2}) \hat{\mathbf{z}} & (8g) & \text{N I} \\
\mathbf{B}_{24} &= -(y_3 - \tfrac{1}{2}) \mathbf{a}_1 + x_3 \mathbf{a}_2 - (z_3 - \tfrac{1}{2}) \mathbf{a}_3 = -a(y_3 - \tfrac{1}{2}) \hat{\mathbf{x}} + ax_3 \hat{\mathbf{y}} - c(z_3 - \tfrac{1}{2}) \hat{\mathbf{z}} & (8g) & \text{N I} \\
\mathbf{B}_{25} &= x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3 = ax_4 \hat{\mathbf{x}} + ay_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}} & (8g) & \text{P I} \\
\mathbf{B}_{26} &= -(x_4 - \tfrac{1}{2}) \mathbf{a}_1 - (y_4 - \tfrac{1}{2}) \mathbf{a}_2 + z_4 \mathbf{a}_3 = -a(x_4 - \tfrac{1}{2}) \hat{\mathbf{x}} - a(y_4 - \tfrac{1}{2}) \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}} & (8g) & \text{P I} \\
\mathbf{B}_{27} &= -y_4 \mathbf{a}_1 + (x_4 + \tfrac{1}{2}) \mathbf{a}_2 + (z_4 + \tfrac{1}{2}) \mathbf{a}_3 = -ay_4 \hat{\mathbf{x}} + a(x_4 + \tfrac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \tfrac{1}{2}) \hat{\mathbf{z}} & (8g) & \text{P I} \\
\mathbf{B}_{28} &= (y_4 + \tfrac{1}{2}) \mathbf{a}_1 - x_4 \mathbf{a}_2 + (z_4 + \tfrac{1}{2}) \mathbf{a}_3 = a(y_4 + \tfrac{1}{2}) \hat{\mathbf{x}} - ax_4 \hat{\mathbf{y}} + c(z_4 + \tfrac{1}{2}) \hat{\mathbf{z}} & (8g) & \text{P I} \\
\mathbf{B}_{29} &= -x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3 = -ax_4 \hat{\mathbf{x}} - ay_4 \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}} & (8g) & \text{P I} \\
\mathbf{B}_{30} &= (x_4 + \tfrac{1}{2}) \mathbf{a}_1 + (y_4 + \tfrac{1}{2}) \mathbf{a}_2 - z_4 \mathbf{a}_3 = a(x_4 + \tfrac{1}{2}) \hat{\mathbf{x}} + a(y_4 + \tfrac{1}{2}) \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}} & (8g) & \text{P I} \\
\mathbf{B}_{31} &= y_4 \mathbf{a}_1 - (x_4 - \tfrac{1}{2}) \mathbf{a}_2 - (z_4 - \tfrac{1}{2}) \mathbf{a}_3 = ay_4 \hat{\mathbf{x}} - a(x_4 - \tfrac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \tfrac{1}{2}) \hat{\mathbf{z}} & (8g) & \text{P I} \\
\mathbf{B}_{32} &= -(y_4 - \tfrac{1}{2}) \mathbf{a}_1 + x_4 \mathbf{a}_2 - (z_4 - \tfrac{1}{2}) \mathbf{a}_3 = -a(y_4 - \tfrac{1}{2}) \hat{\mathbf{x}} + ax_4 \hat{\mathbf{y}} - c(z_4 - \tfrac{1}{2}) \hat{\mathbf{z}} & (8g) & \text{P I}
\end{aligned}$$

References

- [1] J. A. A. Ketelaar and T. A. de Vries, *The crystal structure of tetra phosphonitrile chloride, $P_4N_4Cl_8$* , Recueil Trav. Chimiq. des Pays-Bas **58**, 1081–1099 (1939), doi:10.1002/recl.19390581205.

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