$Li_2Si_2O_5$ Structure: A2B5C2_oC36_37_d_c2d_d-001

This structure previously used the label(s) `A2B5C2_oC36_37_d_c2d_d`. Calls to these addresses will be redirected here.

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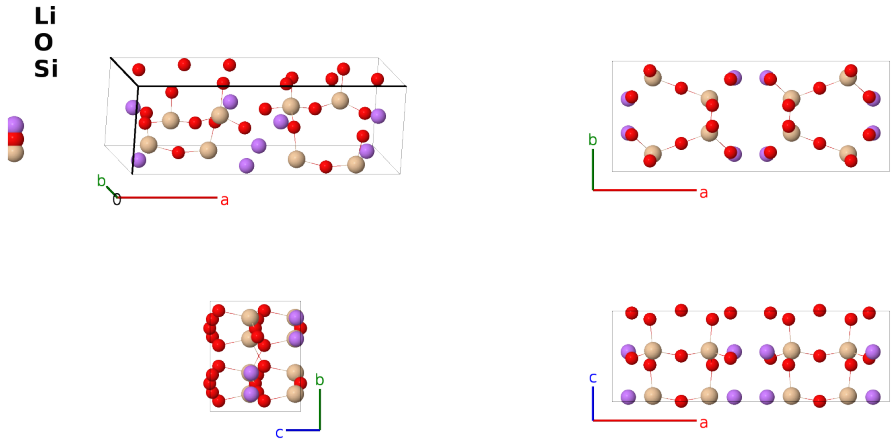
https://aflow.org/prototype-encyclopedia/JE1T

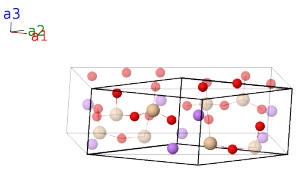
https://aflow.org/prototype-encyclopedia/A2B5C2_oC36_37_d_c2d_d-001



Prototype	$Li_2O_5Si_2$
AFLOW prototype label	A2B5C2_oC36_37_d_c2d_d-001
ICSD	78562
CCDC	1638838
Pearson symbol	oC36
Space group number	37
Space group symbol	$Ccc2$
AFLOW prototype command	`aflow --proto=A2B5C2_oC36_37_d_c2d_d-001 --params=`$a, b/a, c/a, z_1, x_2, y_2, z_2, x_3, y_3, z_3, x_4, y_4, z_4, x_5, y_5, z_5$

Base-centered Orthorhombic primitive vectors

$$\mathbf{a_1} = \frac{1}{2}a\,\hat{\mathbf{x}} - \frac{1}{2}b\,\hat{\mathbf{y}}$$
$$\mathbf{a_2} = \frac{1}{2}a\,\hat{\mathbf{x}} + \frac{1}{2}b\,\hat{\mathbf{y}}$$
$$\mathbf{a_3} = c\,\hat{\mathbf{z}}$$



Basis vectors

		Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B_1}$	=	$\frac{1}{2}\,\mathbf{a}_2 + z_1\,\mathbf{a}_3$	=	$\frac{1}{4}a\,\hat{\mathbf{x}} + \frac{1}{4}b\,\hat{\mathbf{y}} + cz_1\,\hat{\mathbf{z}}$	(4c)	O I
$\mathbf{B_2}$	=	$\frac{1}{2}\,\mathbf{a}_1 + \left(z_1 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$\frac{1}{4}a\,\hat{\mathbf{x}} - \frac{1}{4}b\,\hat{\mathbf{y}} + c\left(z_1 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(4c)	O I
$\mathbf{B_3}$	=	$(x_2 - y_2)\,\mathbf{a}_1 + (x_2 + y_2)\,\mathbf{a}_2 + z_2\,\mathbf{a}_3$	=	$ax_2\,\hat{\mathbf{x}} + by_2\,\hat{\mathbf{y}} + cz_2\,\hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B_4}$	=	$-(x_2 - y_2)\,\mathbf{a}_1 - (x_2 + y_2)\,\mathbf{a}_2 + z_2\,\mathbf{a}_3$	=	$-ax_2\,\hat{\mathbf{x}} - by_2\,\hat{\mathbf{y}} + cz_2\,\hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B_5}$	=	$(x_2 + y_2)\,\mathbf{a}_1 + (x_2 - y_2)\,\mathbf{a}_2 + \left(z_2 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$ax_2\,\hat{\mathbf{x}} - by_2\,\hat{\mathbf{y}} + c\left(z_2 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B_6}$	=	$-(x_2 + y_2)\,\mathbf{a}_1 - (x_2 - y_2)\,\mathbf{a}_2 + \left(z_2 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$-ax_2\,\hat{\mathbf{x}} + by_2\,\hat{\mathbf{y}} + c\left(z_2 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B_7}$	=	$(x_3 - y_3)\,\mathbf{a}_1 + (x_3 + y_3)\,\mathbf{a}_2 + z_3\,\mathbf{a}_3$	=	$ax_3\,\hat{\mathbf{x}} + by_3\,\hat{\mathbf{y}} + cz_3\,\hat{\mathbf{z}}$	(8d)	O II
$\mathbf{B_8}$	=	$-(x_3 - y_3)\,\mathbf{a}_1 - (x_3 + y_3)\,\mathbf{a}_2 + z_3\,\mathbf{a}_3$	=	$-ax_3\,\hat{\mathbf{x}} - by_3\,\hat{\mathbf{y}} + cz_3\,\hat{\mathbf{z}}$	(8d)	O II
$\mathbf{B_9}$	=	$(x_3 + y_3)\,\mathbf{a}_1 + (x_3 - y_3)\,\mathbf{a}_2 + \left(z_3 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$ax_3\,\hat{\mathbf{x}} - by_3\,\hat{\mathbf{y}} + c\left(z_3 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(8d)	O II
$\mathbf{B_{10}}$	=	$-(x_3 + y_3)\,\mathbf{a}_1 - (x_3 - y_3)\,\mathbf{a}_2 + \left(z_3 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$-ax_3\,\hat{\mathbf{x}} + by_3\,\hat{\mathbf{y}} + c\left(z_3 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(8d)	O II
$\mathbf{B_{11}}$	=	$(x_4 - y_4)\,\mathbf{a}_1 + (x_4 + y_4)\,\mathbf{a}_2 + z_4\,\mathbf{a}_3$	=	$ax_4\,\hat{\mathbf{x}} + by_4\,\hat{\mathbf{y}} + cz_4\,\hat{\mathbf{z}}$	(8d)	O III
$\mathbf{B_{12}}$	=	$-(x_4 - y_4)\,\mathbf{a}_1 - (x_4 + y_4)\,\mathbf{a}_2 + z_4\,\mathbf{a}_3$	=	$-ax_4\,\hat{\mathbf{x}} - by_4\,\hat{\mathbf{y}} + cz_4\,\hat{\mathbf{z}}$	(8d)	O III
$\mathbf{B_{13}}$	=	$(x_4 + y_4)\,\mathbf{a}_1 + (x_4 - y_4)\,\mathbf{a}_2 + \left(z_4 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$ax_4\,\hat{\mathbf{x}} - by_4\,\hat{\mathbf{y}} + c\left(z_4 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(8d)	O III
$\mathbf{B_{14}}$	=	$-(x_4 + y_4)\,\mathbf{a}_1 - (x_4 - y_4)\,\mathbf{a}_2 + \left(z_4 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$-ax_4\,\hat{\mathbf{x}} + by_4\,\hat{\mathbf{y}} + c\left(z_4 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(8d)	O III
$\mathbf{B_{15}}$	=	$(x_5 - y_5)\,\mathbf{a}_1 + (x_5 + y_5)\,\mathbf{a}_2 + z_5\,\mathbf{a}_3$	=	$ax_5\,\hat{\mathbf{x}} + by_5\,\hat{\mathbf{y}} + cz_5\,\hat{\mathbf{z}}$	(8d)	Si I
$\mathbf{B_{16}}$	=	$-(x_5 - y_5)\,\mathbf{a}_1 - (x_5 + y_5)\,\mathbf{a}_2 + z_5\,\mathbf{a}_3$	=	$-ax_5\,\hat{\mathbf{x}} - by_5\,\hat{\mathbf{y}} + cz_5\,\hat{\mathbf{z}}$	(8d)	Si I
$\mathbf{B_{17}}$	=	$(x_5 + y_5)\,\mathbf{a}_1 + (x_5 - y_5)\,\mathbf{a}_2 + \left(z_5 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$ax_5\,\hat{\mathbf{x}} - by_5\,\hat{\mathbf{y}} + c\left(z_5 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(8d)	Si I
$\mathbf{B_{18}}$	=	$-(x_5 + y_5)\,\mathbf{a}_1 - (x_5 - y_5)\,\mathbf{a}_2 + \left(z_5 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$-ax_5\,\hat{\mathbf{x}} + by_5\,\hat{\mathbf{y}} + c\left(z_5 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(8d)	Si I

References

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Found in

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