

α -Bi₂O₃ Structure:

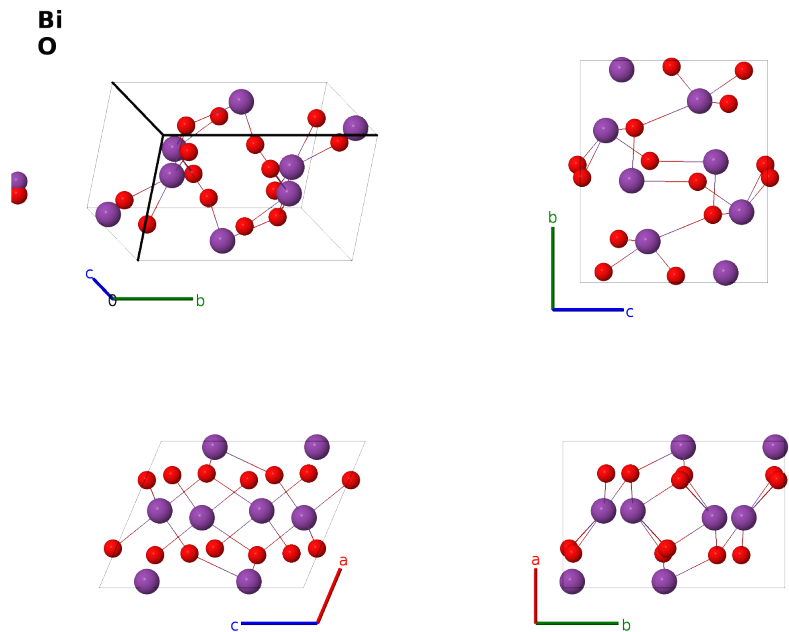
A2B3_mP20_14_2e_3e-003

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<https://aflow.org/prototype-encyclopedia/7G59>

https://aflow.org/prototype-encyclopedia/A2B3_mP20_14_2e_3e-003

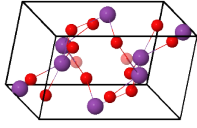


Prototype	Bi ₂ O ₃
AFLOW prototype label	A2B3_mP20_14_2e_3e-003
ICSD	2374
CCDC	1592276
Pearson symbol	mP20
Space group number	14
Space group symbol	$P2_1/c$
AFLOW prototype command	<pre>aflow --proto=A2B3_mP20_14_2e_3e-003 --params=a, b/a, c/a, β, $x_1, y_1, z_1, x_2, y_2, z_2, x_3, y_3, z_3, x_4, y_4, z_4, x_5, y_5, z_5$</pre>

- Bi₂O₃ can be found in at least six forms (Harwig, 1978; Locherer, 2011):
 - monoclinic α -Bi₂O₃, the ground state, stable up to 729° (this structure),
 - tetragonal β -Bi₂O₃, $D5_{12}$, a metastable state observed at 650°C,

- body-centered cubic γ -Bi₂O₃, another metastable phase observed at 639°C,
 - face-centered cubic δ -Bi₂O₃, the stable phase from 729° up to the melting point at 824°C,
 - a high-pressure HP-Bi₂O₃, and
 - a second “non-quenchable” high-pressure structure, HPC-Bi₂O₃.
- α -Bi₂O₃ has the same AFLOW label, A2B3_mP20_14_2e_3e, as orpiment (As₂S₃, $D5_f$). In addition, Pb₂O₃ shares the same Wyckoff positions with these two structures. The structures are generated by the same symmetry operations with different sets of parameters (`--params`) specified in their corresponding CIF files.

Simple Monoclinic primitive vectors

$$\begin{aligned}
 \mathbf{a}_1 &= a \hat{\mathbf{x}} \\
 \mathbf{a}_2 &= b \hat{\mathbf{y}} \\
 \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}
 \end{aligned}$$


Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	=	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Bi I
$\mathbf{B}_2$	$-x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Bi I
$\mathbf{B}_3$	$-x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	=	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Bi I
$\mathbf{B}_4$	$x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Bi I
$\mathbf{B}_5$	$x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	=	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	Bi II
$\mathbf{B}_6$	$-x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Bi II
$\mathbf{B}_7$	$-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	=	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	Bi II
$\mathbf{B}_8$	$x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Bi II
$\mathbf{B}_9$	$x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	=	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_{10}$	$-x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_{11}$	$-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	=	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_{12}$	$x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_{13}$	$x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	=	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{14}$	$-x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{15}$	$-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	=	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	O II

$$\begin{aligned}
\mathbf{B}_{16} &= x_4 \mathbf{a}_1 - \left(y_4 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_4 + \frac{1}{2}\right) \mathbf{a}_3 = \begin{pmatrix} (ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4e) & \text{O II} \\
\mathbf{B}_{17} &= x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3 = (ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}} & (4e) & \text{O III} \\
\mathbf{B}_{18} &= -x_5 \mathbf{a}_1 + \left(y_5 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_5 - \frac{1}{2}\right) \mathbf{a}_3 = \begin{pmatrix} -(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + \\ b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4e) & \text{O III} \\
\mathbf{B}_{19} &= -x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3 = -(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}} & (4e) & \text{O III} \\
\mathbf{B}_{20} &= x_5 \mathbf{a}_1 - \left(y_5 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_5 + \frac{1}{2}\right) \mathbf{a}_3 = \begin{pmatrix} (ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4e) & \text{O III}
\end{aligned}$$

References

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First cited in

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