

KPF₆ Structure:

A24BC_cF104_209_j_a_b-001

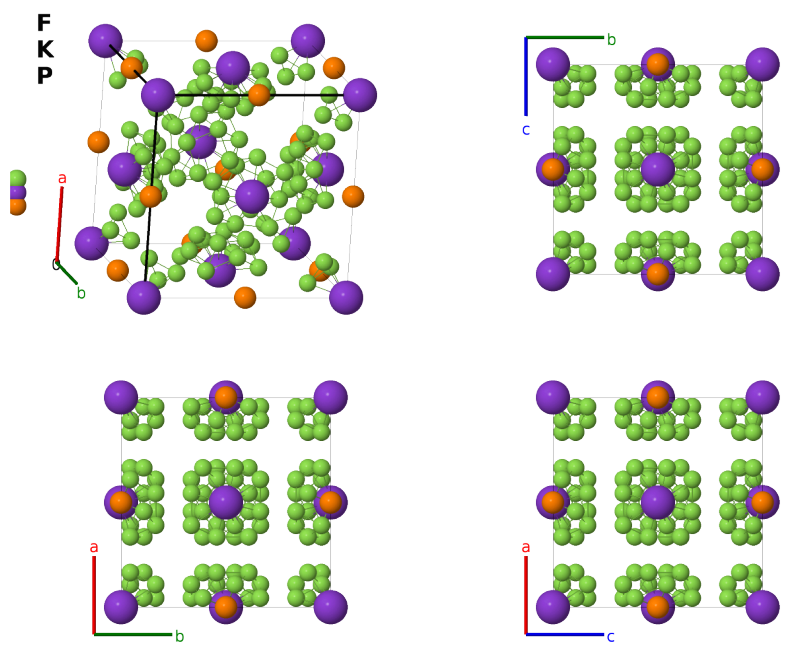
This structure previously used the label(s) **A24BC_cF104_209_j_a_b**. Calls to these addresses will be redirected here.

Cite this page as:

- H. Eckert, S. Divilov, M. J. Mehl, D. Hicks, A. C. Zettl, M. Esters, X. Campilongo, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*, Comput. Mater. Sci. **240**, 112988 (2024), doi: 10.1016/j.commatsci.2024.112988.
- D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

<https://aflow.org/prototype-encyclopedia/XBGM>

https://aflow.org/prototype-encyclopedia/A24BC_cF104_209_j_a_b-001



Prototype	F ₆ KP
AFLOW prototype label	A24BC_cF104_209_j_a_b-001
Pearson symbol	cF104
Space group number	209
Space group symbol	F432
AFLOW prototype command	<code>aflow --proto=A24BC_cF104_209_j_a_b-001</code> <code>--params=a, x₃, y₃, z₃</code>

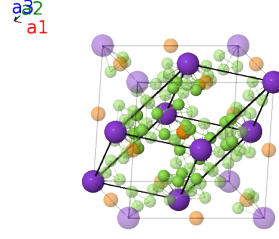
- The (96j) Wyckoff positions are decorated by F atoms with a site occupation of 0.25, hence the prototype material is KPF₆ rather than KPF₂₄.

Face-centered Cubic primitive vectors

$$\mathbf{a}_1 = \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}}$$

$$\mathbf{a}_2 = \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{z}}$$

$$\mathbf{a}_3 = \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$=$	0	$=$	0	(4a) K I
$\mathbf{B}_2$	$=$	$\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}}$	(4b) P I
$\mathbf{B}_3$	$=$	$(-x_3 + y_3 + z_3) \mathbf{a}_1 +$ $(x_3 - y_3 + z_3) \mathbf{a}_2 +$ $(x_3 + y_3 - z_3) \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} + ay_3 \hat{\mathbf{y}} + az_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_4$	$=$	$(x_3 - y_3 + z_3) \mathbf{a}_1 +$ $(-x_3 + y_3 + z_3) \mathbf{a}_2 -$ $(x_3 + y_3 + z_3) \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} - ay_3 \hat{\mathbf{y}} + az_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_5$	$=$	$(x_3 + y_3 - z_3) \mathbf{a}_1 -$ $(x_3 + y_3 + z_3) \mathbf{a}_2 +$ $(-x_3 + y_3 + z_3) \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} + ay_3 \hat{\mathbf{y}} - az_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_6$	$=$	$-(x_3 + y_3 + z_3) \mathbf{a}_1 +$ $(x_3 + y_3 - z_3) \mathbf{a}_2 +$ $(x_3 - y_3 + z_3) \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} - ay_3 \hat{\mathbf{y}} - az_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_7$	$=$	$(x_3 + y_3 - z_3) \mathbf{a}_1 +$ $(-x_3 + y_3 + z_3) \mathbf{a}_2 +$ $(x_3 - y_3 + z_3) \mathbf{a}_3$	$=$	$az_3 \hat{\mathbf{x}} + ax_3 \hat{\mathbf{y}} + ay_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_8$	$=$	$-(x_3 + y_3 + z_3) \mathbf{a}_1 +$ $(x_3 - y_3 + z_3) \mathbf{a}_2 +$ $(-x_3 + y_3 + z_3) \mathbf{a}_3$	$=$	$az_3 \hat{\mathbf{x}} - ax_3 \hat{\mathbf{y}} - ay_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_9$	$=$	$(-x_3 + y_3 + z_3) \mathbf{a}_1 +$ $(x_3 + y_3 - z_3) \mathbf{a}_2 -$ $(x_3 + y_3 + z_3) \mathbf{a}_3$	$=$	$-az_3 \hat{\mathbf{x}} - ax_3 \hat{\mathbf{y}} + ay_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_{10}$	$=$	$(x_3 - y_3 + z_3) \mathbf{a}_1 -$ $(x_3 + y_3 + z_3) \mathbf{a}_2 +$ $(x_3 + y_3 - z_3) \mathbf{a}_3$	$=$	$-az_3 \hat{\mathbf{x}} + ax_3 \hat{\mathbf{y}} - ay_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_{11}$	$=$	$(x_3 - y_3 + z_3) \mathbf{a}_1 +$ $(x_3 + y_3 - z_3) \mathbf{a}_2 +$ $(-x_3 + y_3 + z_3) \mathbf{a}_3$	$=$	$ay_3 \hat{\mathbf{x}} + az_3 \hat{\mathbf{y}} + ax_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_{12}$	$=$	$(-x_3 + y_3 + z_3) \mathbf{a}_1 -$ $(x_3 + y_3 + z_3) \mathbf{a}_2 +$ $(x_3 - y_3 + z_3) \mathbf{a}_3$	$=$	$-ay_3 \hat{\mathbf{x}} + az_3 \hat{\mathbf{y}} - ax_3 \hat{\mathbf{z}}$	(96j) F I
$\mathbf{B}_{13}$	$=$	$-(x_3 + y_3 + z_3) \mathbf{a}_1 +$ $(-x_3 + y_3 + z_3) \mathbf{a}_2 +$ $(x_3 + y_3 - z_3) \mathbf{a}_3$	$=$	$ay_3 \hat{\mathbf{x}} - az_3 \hat{\mathbf{y}} - ax_3 \hat{\mathbf{z}}$	(96j) F I

$$\begin{aligned}
\mathbf{B}_{14} &= \begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_3 &= -ay_3 \hat{\mathbf{x}} - az_3 \hat{\mathbf{y}} + ax_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{15} &= \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_3 &= ay_3 \hat{\mathbf{x}} + ax_3 \hat{\mathbf{y}} - az_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{16} &= -\begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 - y_3 - z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 - y_3 - z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_3 &= -ay_3 \hat{\mathbf{x}} - ax_3 \hat{\mathbf{y}} - az_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{17} &= -\begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 + y_3 + z_3 \\ x_3 - y_3 + z_3 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 + y_3 + z_3 \\ x_3 - y_3 + z_3 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_3 &= ay_3 \hat{\mathbf{x}} - ax_3 \hat{\mathbf{y}} + az_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{18} &= \begin{pmatrix} x_3 + y_3 + z_3 \\ x_3 + y_3 - z_3 \\ x_3 - y_3 - z_3 \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_3 + y_3 + z_3 \\ x_3 + y_3 - z_3 \\ x_3 - y_3 - z_3 \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 + y_3 - z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_3 &= -ay_3 \hat{\mathbf{x}} + ax_3 \hat{\mathbf{y}} + az_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{19} &= -\begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 - y_3 - z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 - y_3 - z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 + y_3 + z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_3 &= ax_3 \hat{\mathbf{x}} + az_3 \hat{\mathbf{y}} - ay_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{20} &= \begin{pmatrix} x_3 + y_3 + z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_3 + y_3 + z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 + y_3 - z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_3 &= -ax_3 \hat{\mathbf{x}} + az_3 \hat{\mathbf{y}} + ay_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{21} &= \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 + y_3 - z_3 \\ x_3 - y_3 + z_3 \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 + y_3 - z_3 \\ x_3 - y_3 + z_3 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 + y_3 - z_3 \\ x_3 - y_3 - z_3 \end{pmatrix} \mathbf{a}_3 &= -ax_3 \hat{\mathbf{x}} - az_3 \hat{\mathbf{y}} - ay_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{22} &= -\begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \\ x_3 - y_3 - z_3 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \\ x_3 - y_3 - z_3 \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \\ x_3 - y_3 - z_3 \end{pmatrix} \mathbf{a}_3 &= ax_3 \hat{\mathbf{x}} - az_3 \hat{\mathbf{y}} + ay_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{23} &= -\begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 + y_3 - z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 + y_3 - z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 + y_3 + z_3 \\ x_3 - y_3 + z_3 \end{pmatrix} \mathbf{a}_3 &= az_3 \hat{\mathbf{x}} + ay_3 \hat{\mathbf{y}} - ax_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{24} &= \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 + y_3 + z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 + y_3 + z_3 \\ x_3 + y_3 - z_3 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 + y_3 + z_3 \\ x_3 - y_3 + z_3 \end{pmatrix} \mathbf{a}_3 &= az_3 \hat{\mathbf{x}} - ay_3 \hat{\mathbf{y}} + ax_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{25} &= \begin{pmatrix} x_3 + y_3 + z_3 \\ x_3 - y_3 - z_3 \\ x_3 - y_3 + z_3 \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_3 + y_3 + z_3 \\ x_3 - y_3 - z_3 \\ x_3 - y_3 + z_3 \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_3 - y_3 + z_3 \\ x_3 - y_3 - z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_3 &= -az_3 \hat{\mathbf{x}} + ay_3 \hat{\mathbf{y}} + ax_3 \hat{\mathbf{z}} & (96j) & \text{F I} \\
\mathbf{B}_{26} &= -\begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 - y_3 - z_3 \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_3 + y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 - y_3 - z_3 \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_3 - y_3 - z_3 \\ x_3 - y_3 + z_3 \\ x_3 + y_3 + z_3 \end{pmatrix} \mathbf{a}_3 &= -az_3 \hat{\mathbf{x}} - ay_3 \hat{\mathbf{y}} - ax_3 \hat{\mathbf{z}} & (96j) & \text{F I}
\end{aligned}$$

References

- [1] Y. P. Mascarenhas and S. H. Pulcinelli, *A redetermination of the structure of α -potassium fluorophosphate*, Acta Cryst. **37**, C175 (1981), doi:10.1107/S0108767381094294.

Found in

- [1] P. Villars and K. Cenzual, *Pearson's Crystal Data – Crystal Structure Database for Inorganic Compounds* (2013). ASM International.

First cited in

D. Hicks, M. J. Mehl, E. Gossett, C. Toher, O. Levy, R. M. Hanson, G. Hart, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 2*, Comput. Mater. Sci. **161**, S1 (2019). doi: 10.1016/j.commatsci.2018.10.043