

Cs₁₁O₃ Structure:

A11B3_mP56_14_11e_3e-001

This structure previously used the label(s) **A11B3_mP56_14_11e_3e**. Calls to these addresses will be redirected here.

Cite this page as:

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- D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

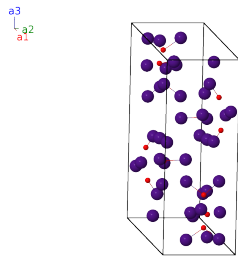
<https://aflow.org/prototype-encyclopedia/2343>

https://aflow.org/prototype-encyclopedia/A11B3_mP56_14_11e_3e-001

Prototype	Cs ₁₁ O ₃
AFLOW prototype label	A11B3_mP56_14_11e_3e-001
ICSD	1077
CCDC	1591267
Pearson symbol	mP56
Space group number	14
Space group symbol	$P2_1/c$
AFLOW prototype command	<pre>aflow --proto=A11B3_mP56_14_11e_3e-001 --params=a,b/a,c/a,β,x₁,y₁,z₁,x₂,y₂,z₂,x₃,y₃,z₃,x₄,y₄,z₄,x₅,y₅,z₅,x₆,y₆,z₆,x₇, y₇,z₇,x₈,y₈,z₈,x₉,y₉,z₉,x₁₀,y₁₀,z₁₀,x₁₁,y₁₁,z₁₁,x₁₂,y₁₂,z₁₂,x₁₃,y₁₃,z₁₃,x₁₄,y₁₄,z₁₄</pre>

Simple Monoclinic primitive vectors

$$\begin{aligned} \mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}} \end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	$=$	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs I
$\mathbf{B}_2$	$= -x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs I
$\mathbf{B}_3$	$= -x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	$=$	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs I

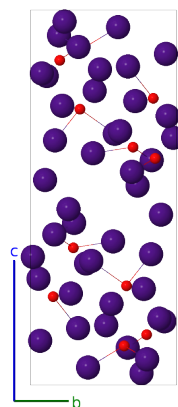
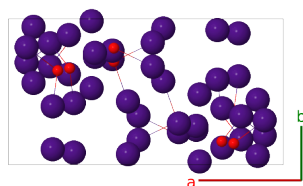
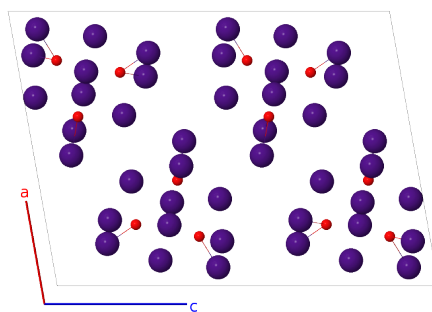
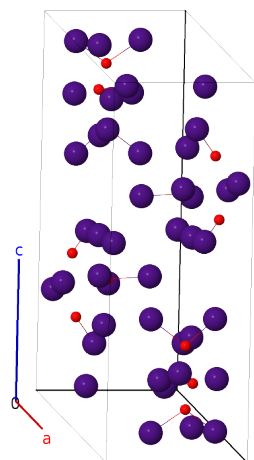
$\mathbf{B}_4$	$=$	$x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} -$ $b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs I
$\mathbf{B}_5$	$=$	$x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs II
$\mathbf{B}_6$	$=$	$-x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 -$ $(z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} +$ $b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs II
$\mathbf{B}_7$	$=$	$-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs II
$\mathbf{B}_8$	$=$	$x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} -$ $b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs II
$\mathbf{B}_9$	$=$	$x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs III
$\mathbf{B}_{10}$	$=$	$-x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 -$ $(z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} +$ $b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs III
$\mathbf{B}_{11}$	$=$	$-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs III
$\mathbf{B}_{12}$	$=$	$x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} -$ $b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs III
$\mathbf{B}_{13}$	$=$	$x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs IV
$\mathbf{B}_{14}$	$=$	$-x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 -$ $(z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} +$ $b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs IV
$\mathbf{B}_{15}$	$=$	$-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs IV
$\mathbf{B}_{16}$	$=$	$x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} -$ $b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs IV
$\mathbf{B}_{17}$	$=$	$x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs V
$\mathbf{B}_{18}$	$=$	$-x_5 \mathbf{a}_1 + (y_5 + \frac{1}{2}) \mathbf{a}_2 -$ $(z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} +$ $b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs V
$\mathbf{B}_{19}$	$=$	$-x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs V
$\mathbf{B}_{20}$	$=$	$x_5 \mathbf{a}_1 - (y_5 - \frac{1}{2}) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} -$ $b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs V
$\mathbf{B}_{21}$	$=$	$x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	$=$	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VI
$\mathbf{B}_{22}$	$=$	$-x_6 \mathbf{a}_1 + (y_6 + \frac{1}{2}) \mathbf{a}_2 -$ $(z_6 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_6 + c(z_6 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} +$ $b(y_6 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VI
$\mathbf{B}_{23}$	$=$	$-x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$	$=$	$-(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VI
$\mathbf{B}_{24}$	$=$	$x_6 \mathbf{a}_1 - (y_6 - \frac{1}{2}) \mathbf{a}_2 + (z_6 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} -$ $b(y_6 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VI
$\mathbf{B}_{25}$	$=$	$x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3$	$=$	$(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VII
$\mathbf{B}_{26}$	$=$	$-x_7 \mathbf{a}_1 + (y_7 + \frac{1}{2}) \mathbf{a}_2 -$ $(z_7 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_7 + c(z_7 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} +$ $b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_7 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VII
$\mathbf{B}_{27}$	$=$	$-x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3$	$=$	$-(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VII
$\mathbf{B}_{28}$	$=$	$x_7 \mathbf{a}_1 - (y_7 - \frac{1}{2}) \mathbf{a}_2 + (z_7 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_7 + c(z_7 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} -$ $b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VII
$\mathbf{B}_{29}$	$=$	$x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3$	$=$	$(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VIII
$\mathbf{B}_{30}$	$=$	$-x_8 \mathbf{a}_1 + (y_8 + \frac{1}{2}) \mathbf{a}_2 -$ $(z_8 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_8 + c(z_8 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} +$ $b(y_8 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_8 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VIII
$\mathbf{B}_{31}$	$=$	$-x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3$	$=$	$-(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VIII
$\mathbf{B}_{32}$	$=$	$x_8 \mathbf{a}_1 - (y_8 - \frac{1}{2}) \mathbf{a}_2 + (z_8 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_8 + c(z_8 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} -$ $b(y_8 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs VIII
$\mathbf{B}_{33}$	$=$	$x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 + z_9 \mathbf{a}_3$	$=$	$(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs IX

$\mathbf{B}_{34} =$	$-x_9 \mathbf{a}_1 + (y_9 + \frac{1}{2}) \mathbf{a}_2 - (z_9 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_9 + c(z_9 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_9 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_9 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs IX
$\mathbf{B}_{35} =$	$-x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 - z_9 \mathbf{a}_3$	$=$	$-(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} - cz_9 \sin \beta \hat{\mathbf{z}}$	(4e)	Cs IX
$\mathbf{B}_{36} =$	$x_9 \mathbf{a}_1 - (y_9 - \frac{1}{2}) \mathbf{a}_2 + (z_9 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_9 + c(z_9 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_9 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_9 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs IX
$\mathbf{B}_{37} =$	$x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3$	$=$	$(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} + cz_{10} \sin \beta \hat{\mathbf{z}}$	(4e)	Cs X
$\mathbf{B}_{38} =$	$-x_{10} \mathbf{a}_1 + (y_{10} + \frac{1}{2}) \mathbf{a}_2 - (z_{10} - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_{10} + c(z_{10} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{10} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{10} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs X
$\mathbf{B}_{39} =$	$-x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3$	$=$	$-(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} - cz_{10} \sin \beta \hat{\mathbf{z}}$	(4e)	Cs X
$\mathbf{B}_{40} =$	$x_{10} \mathbf{a}_1 - (y_{10} - \frac{1}{2}) \mathbf{a}_2 + (z_{10} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{10} + c(z_{10} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{10} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{10} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs X
$\mathbf{B}_{41} =$	$x_{11} \mathbf{a}_1 + y_{11} \mathbf{a}_2 + z_{11} \mathbf{a}_3$	$=$	$(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} + by_{11} \hat{\mathbf{y}} + cz_{11} \sin \beta \hat{\mathbf{z}}$	(4e)	Cs XI
$\mathbf{B}_{42} =$	$-x_{11} \mathbf{a}_1 + (y_{11} + \frac{1}{2}) \mathbf{a}_2 - (z_{11} - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_{11} + c(z_{11} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{11} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{11} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs XI
$\mathbf{B}_{43} =$	$-x_{11} \mathbf{a}_1 - y_{11} \mathbf{a}_2 - z_{11} \mathbf{a}_3$	$=$	$-(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} - by_{11} \hat{\mathbf{y}} - cz_{11} \sin \beta \hat{\mathbf{z}}$	(4e)	Cs XI
$\mathbf{B}_{44} =$	$x_{11} \mathbf{a}_1 - (y_{11} - \frac{1}{2}) \mathbf{a}_2 + (z_{11} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{11} + c(z_{11} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{11} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{11} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Cs XI
$\mathbf{B}_{45} =$	$x_{12} \mathbf{a}_1 + y_{12} \mathbf{a}_2 + z_{12} \mathbf{a}_3$	$=$	$(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} + by_{12} \hat{\mathbf{y}} + cz_{12} \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_{46} =$	$-x_{12} \mathbf{a}_1 + (y_{12} + \frac{1}{2}) \mathbf{a}_2 - (z_{12} - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_{12} + c(z_{12} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{12} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{12} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_{47} =$	$-x_{12} \mathbf{a}_1 - y_{12} \mathbf{a}_2 - z_{12} \mathbf{a}_3$	$=$	$-(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} - by_{12} \hat{\mathbf{y}} - cz_{12} \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_{48} =$	$x_{12} \mathbf{a}_1 - (y_{12} - \frac{1}{2}) \mathbf{a}_2 + (z_{12} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{12} + c(z_{12} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{12} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{12} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_{49} =$	$x_{13} \mathbf{a}_1 + y_{13} \mathbf{a}_2 + z_{13} \mathbf{a}_3$	$=$	$(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} + by_{13} \hat{\mathbf{y}} + cz_{13} \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{50} =$	$-x_{13} \mathbf{a}_1 + (y_{13} + \frac{1}{2}) \mathbf{a}_2 - (z_{13} - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_{13} + c(z_{13} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{13} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{13} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{51} =$	$-x_{13} \mathbf{a}_1 - y_{13} \mathbf{a}_2 - z_{13} \mathbf{a}_3$	$=$	$-(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} - by_{13} \hat{\mathbf{y}} - cz_{13} \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{52} =$	$x_{13} \mathbf{a}_1 - (y_{13} - \frac{1}{2}) \mathbf{a}_2 + (z_{13} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{13} + c(z_{13} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{13} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{13} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{53} =$	$x_{14} \mathbf{a}_1 + y_{14} \mathbf{a}_2 + z_{14} \mathbf{a}_3$	$=$	$(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} + by_{14} \hat{\mathbf{y}} + cz_{14} \sin \beta \hat{\mathbf{z}}$	(4e)	O III
$\mathbf{B}_{54} =$	$-x_{14} \mathbf{a}_1 + (y_{14} + \frac{1}{2}) \mathbf{a}_2 - (z_{14} - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_{14} + c(z_{14} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{14} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{14} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O III
$\mathbf{B}_{55} =$	$-x_{14} \mathbf{a}_1 - y_{14} \mathbf{a}_2 - z_{14} \mathbf{a}_3$	$=$	$-(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} - by_{14} \hat{\mathbf{y}} - cz_{14} \sin \beta \hat{\mathbf{z}}$	(4e)	O III
$\mathbf{B}_{56} =$	$x_{14} \mathbf{a}_1 - (y_{14} - \frac{1}{2}) \mathbf{a}_2 + (z_{14} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{14} + c(z_{14} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{14} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{14} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O III

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